

Competitive Algorithm Design and Practice Shortest Path 2014/03/26

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Outline

- Single Source Shortest Path
 - Relaxation
 - Bellman Ford
 - SPFA
- All Pair Shortest Path
 - Floyd



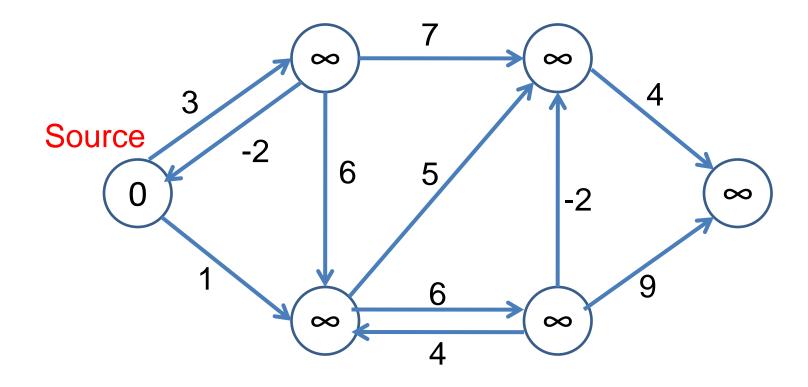


Singe Source Shortest Path



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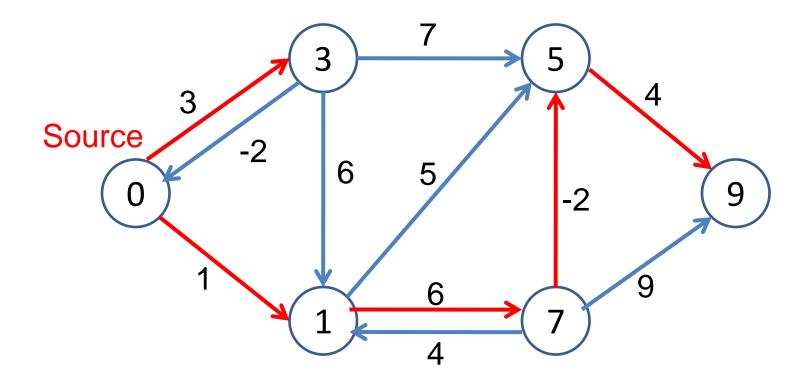
SSSP





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SSSP





SSSP



- How?
 - Greedy?
 - BFS?
 - Backtracking?



SSSP



- How?
 - Greedy? WA if not greedy properly..
 - BFS? WA, only for un-weighted shortest path
 - Backtracking? TLE

See another slide for more details





SSSP - Algorithm

- Bellman Ford
- SPFA
- Dijkstra
- And more...

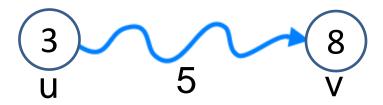








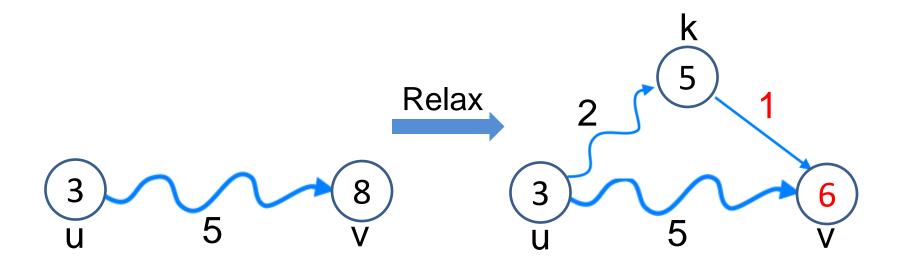
Triangle Inequality







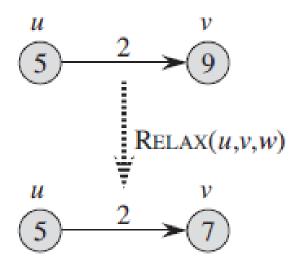
Triangle Inequality



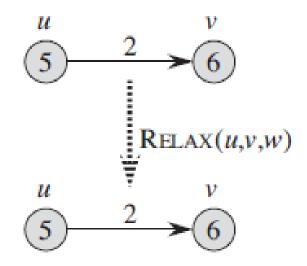




Examples



Shorter than before



Remain unchanged





Pseudo code









- Relax all edges in graph
 - Totally n-1 times





- Relax all edges in graph
 - Totally n-1 times

- Always n-1 times?
 - Stop when all edges stop relaxing





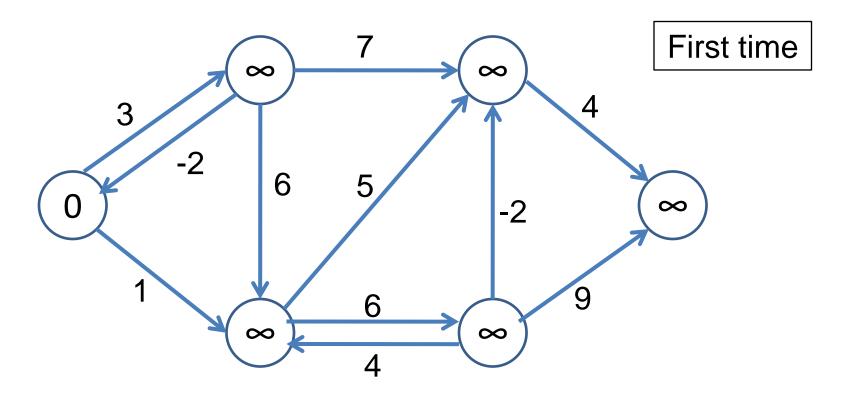
- Relax all edges in graph
 - Totally n-1 times

- Always n-1 times?
 - Stop when all edges stop relaxing

- Complexity
 - -O(VE)

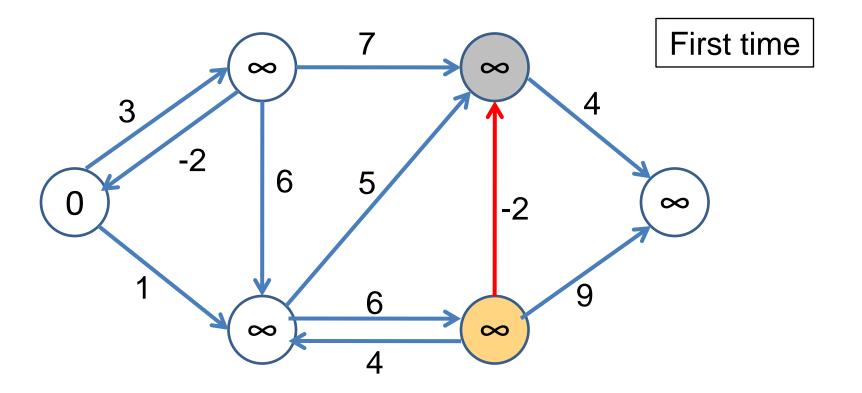






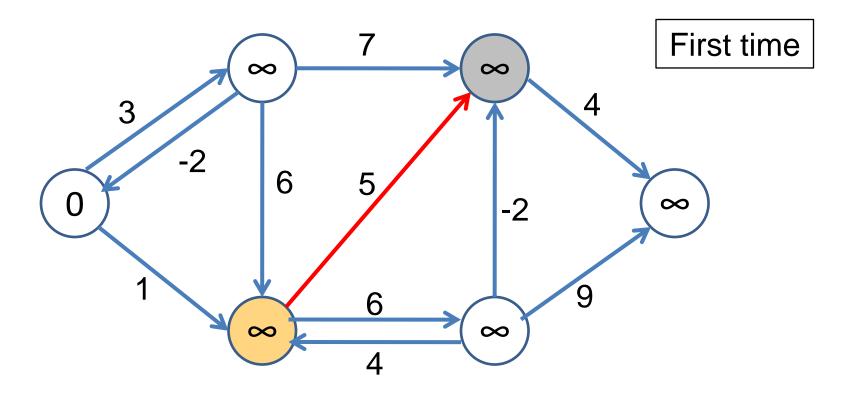






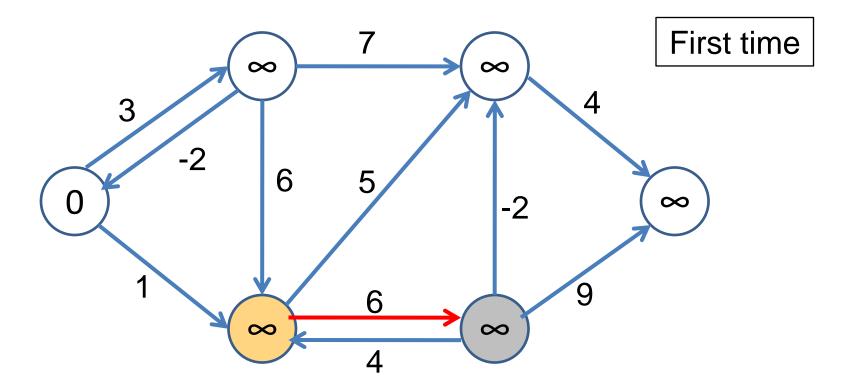






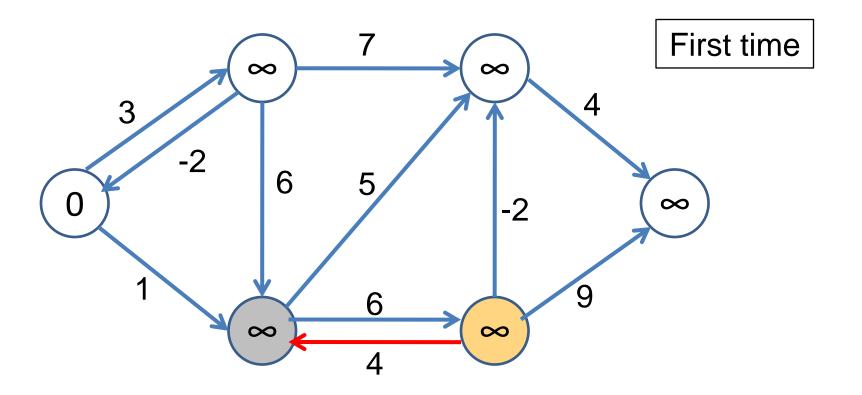






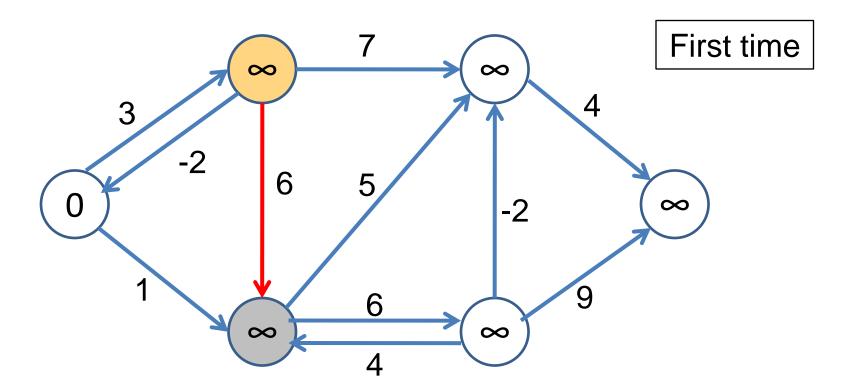






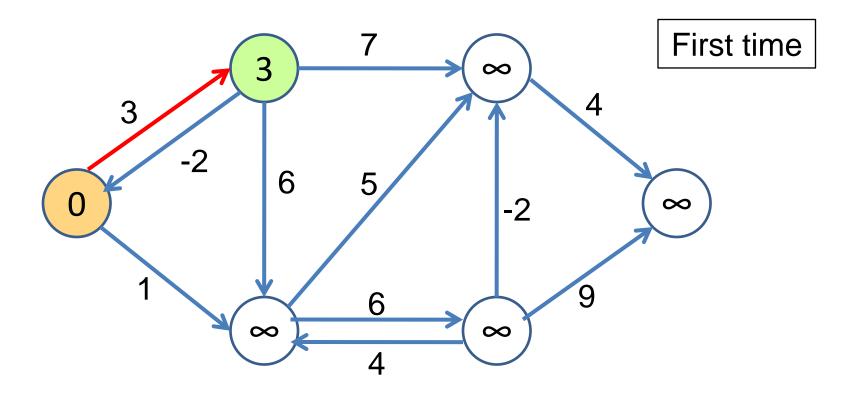






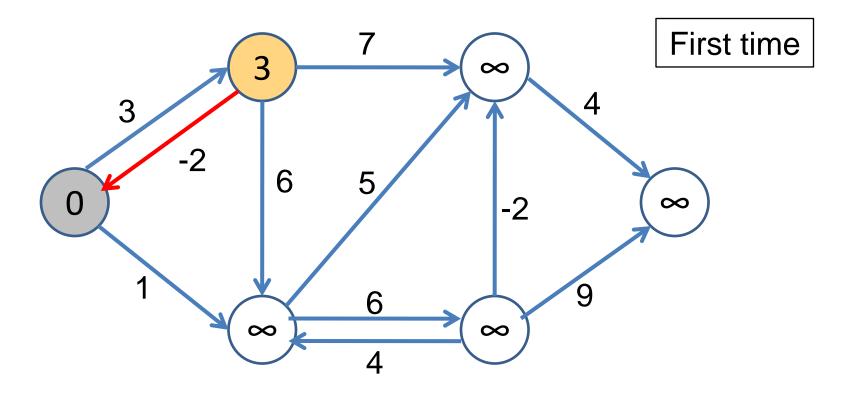






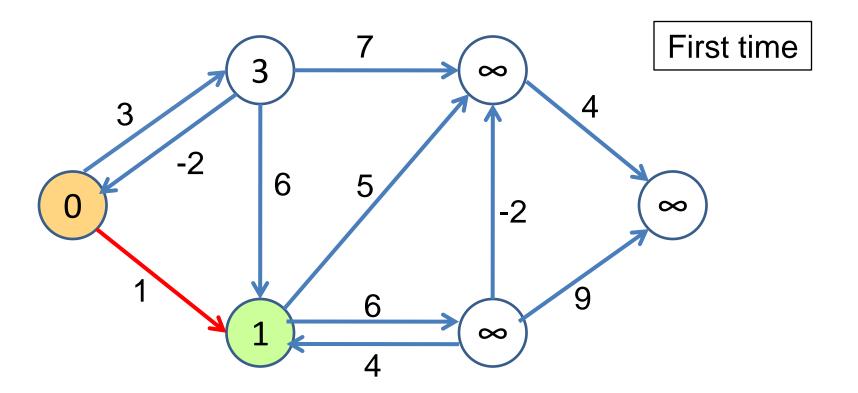






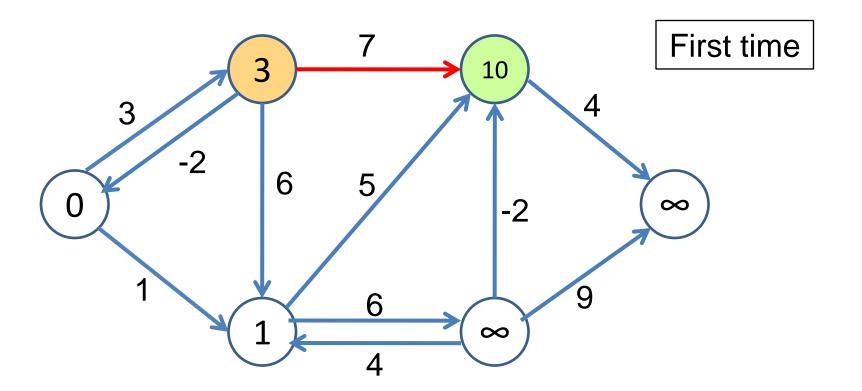






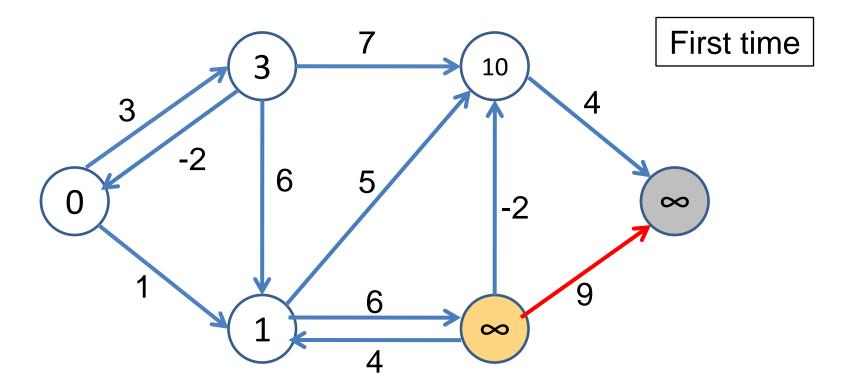






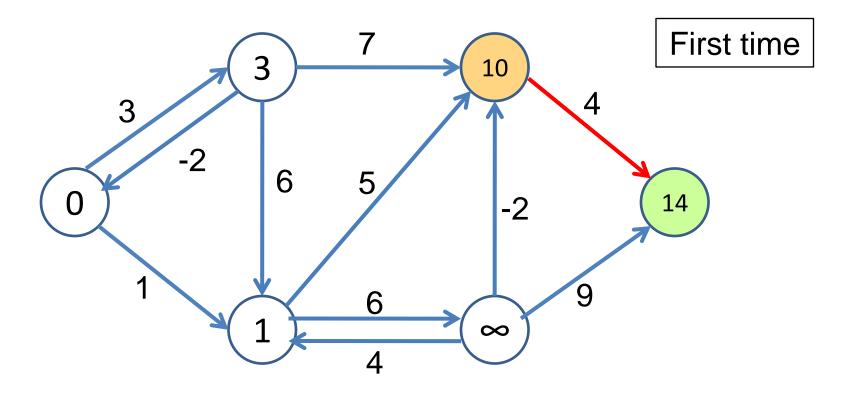






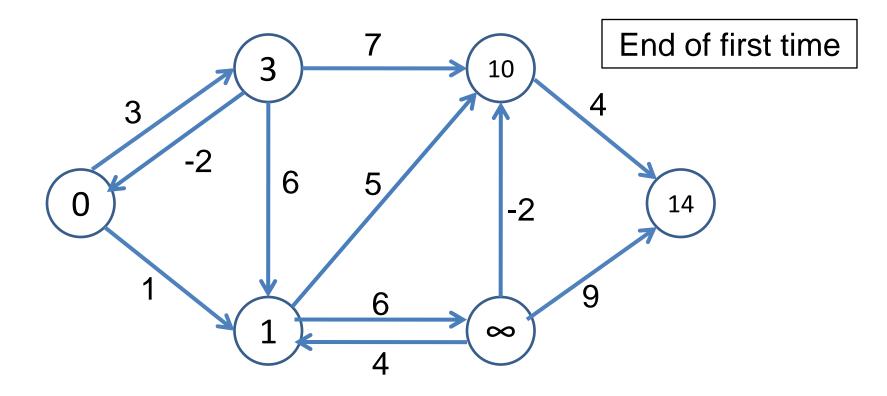






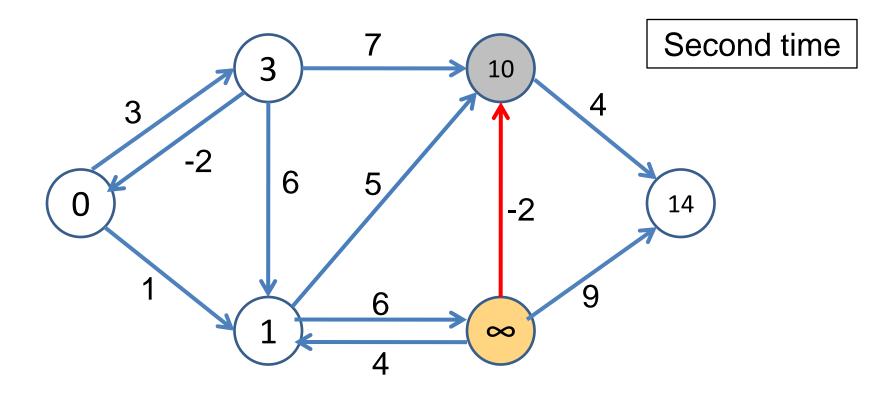






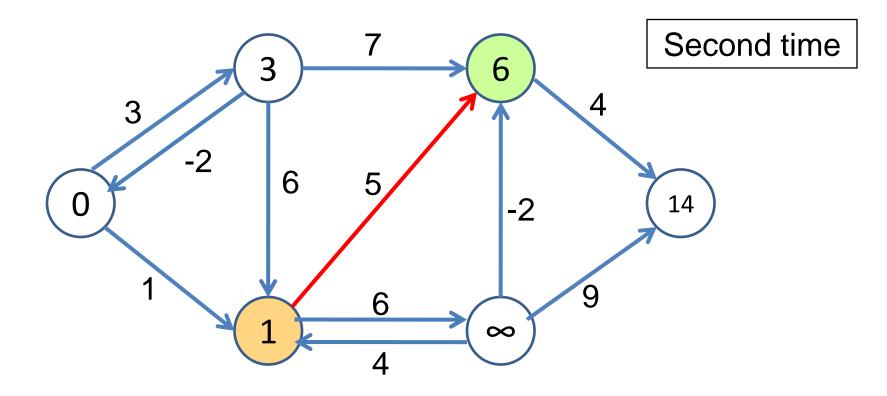






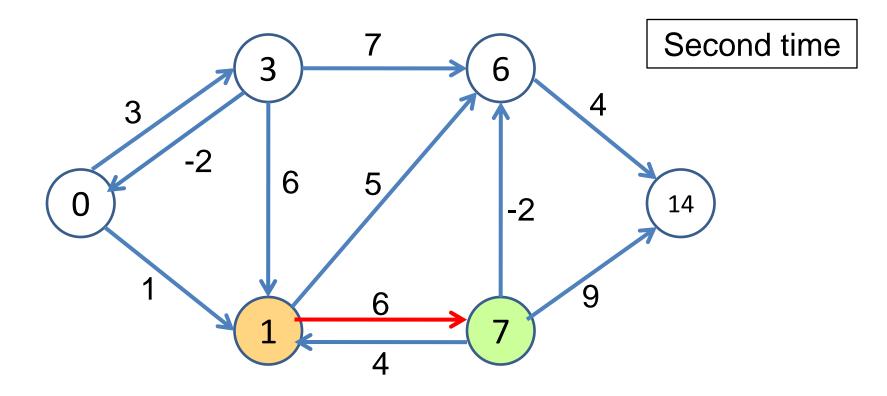






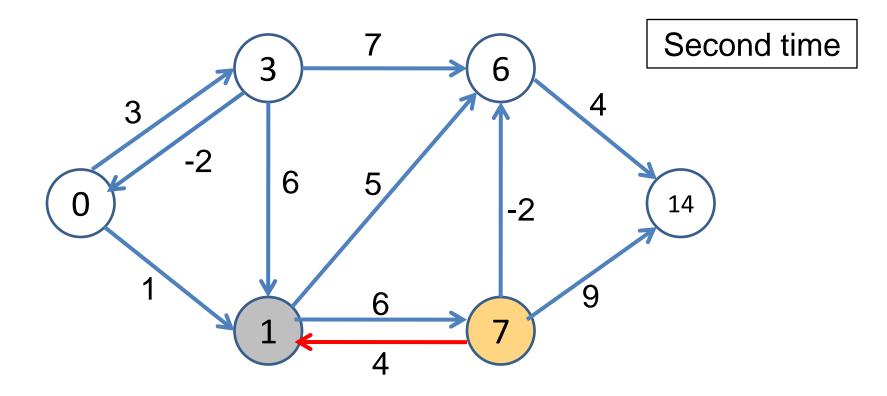






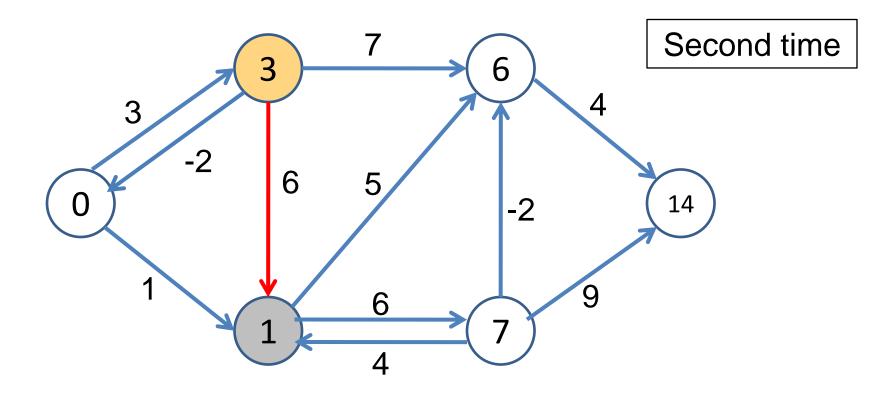






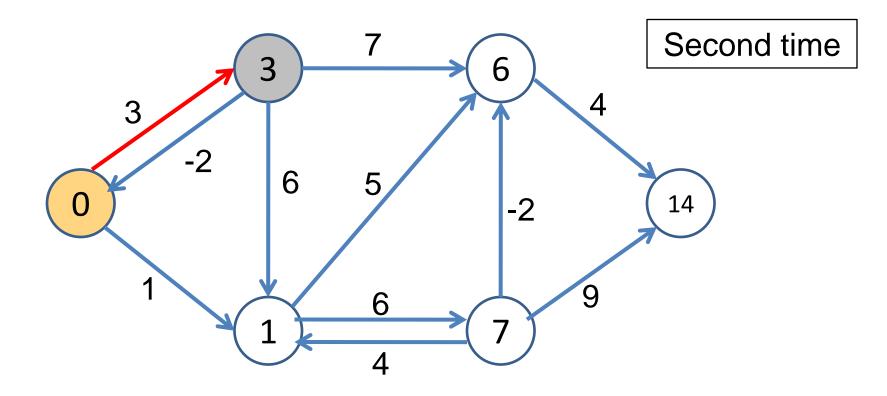






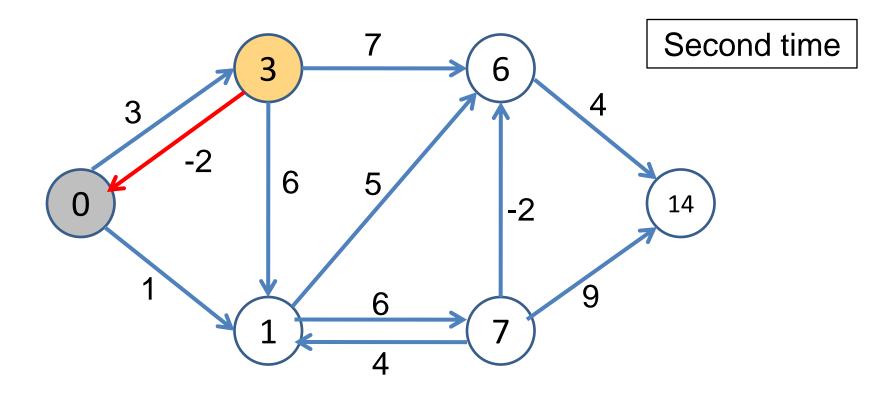






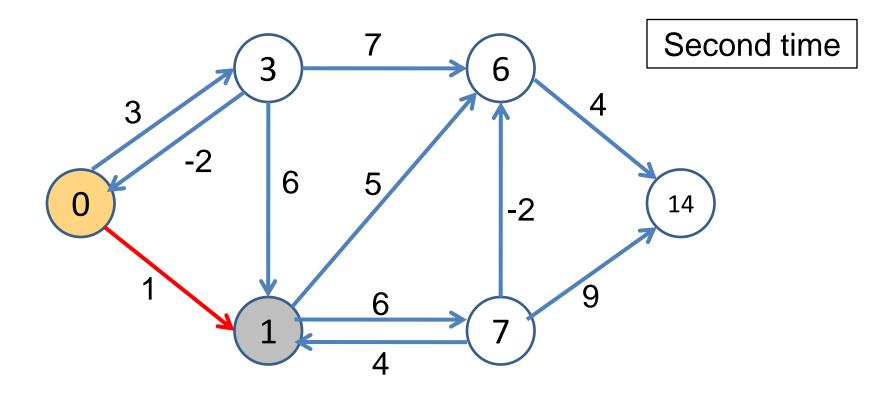






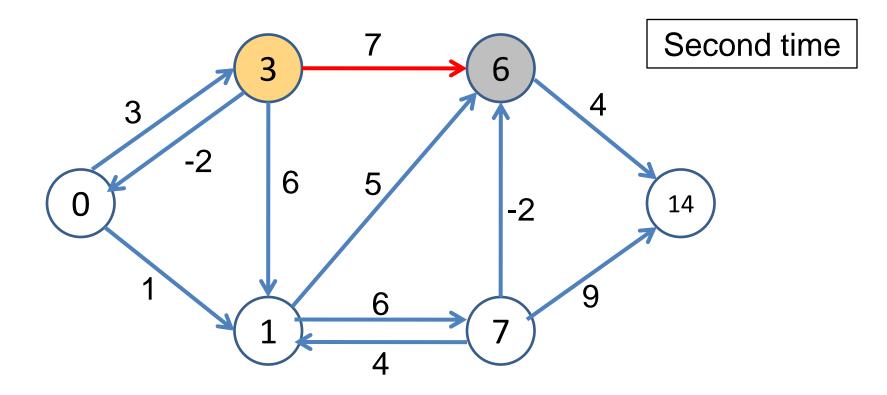






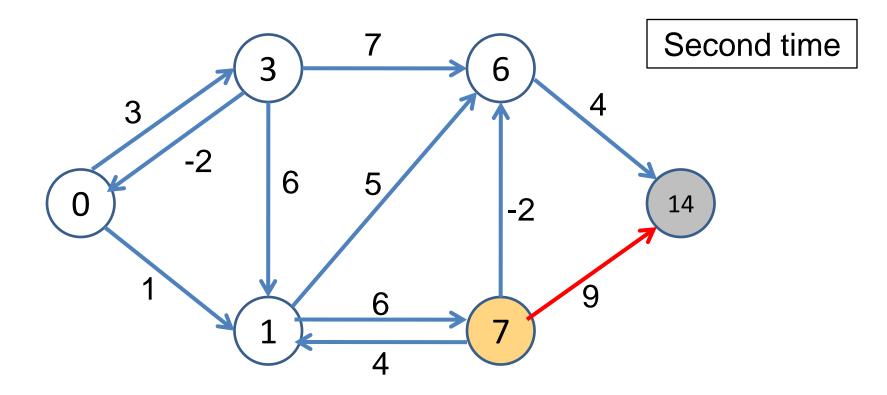






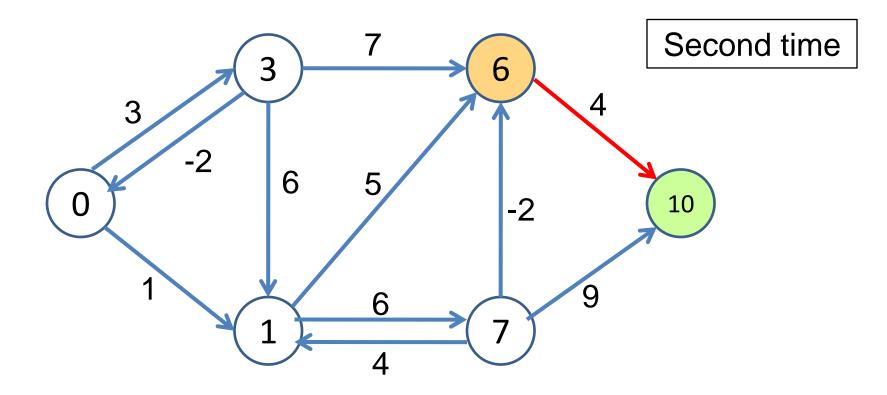






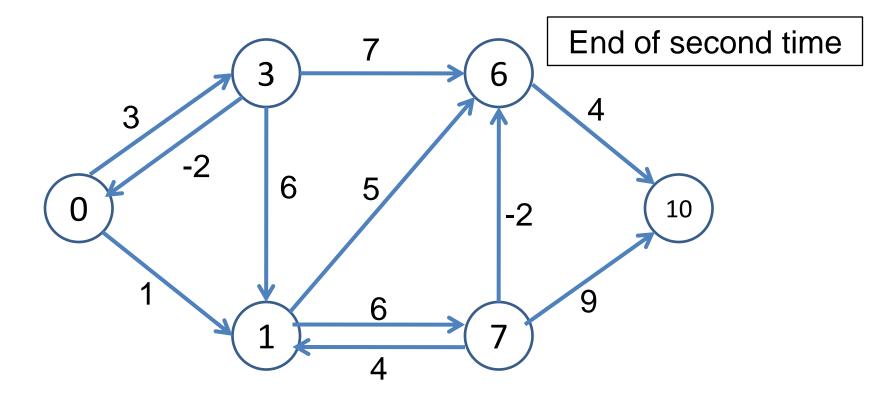






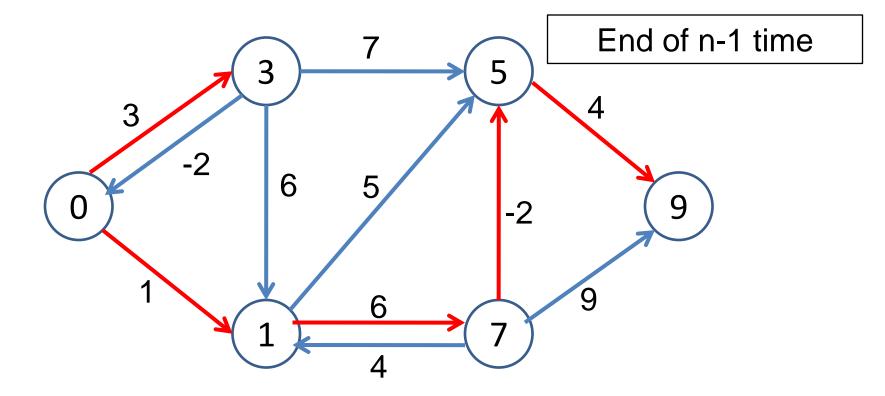














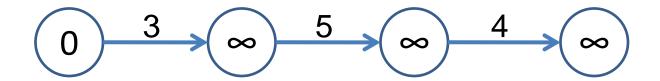


• Why n-1 time(s)?





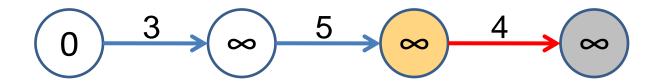
• Why n-1 time(s)?







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• Why n-1 time(s)?

2nd time

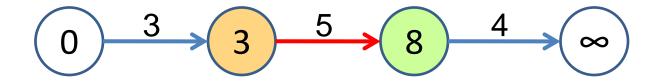






• Why n-1 time(s)?

2nd time







• Why n-1 time(s)?

2nd time

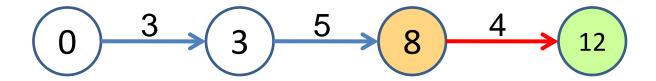






• Why n-1 time(s)?

3rd time

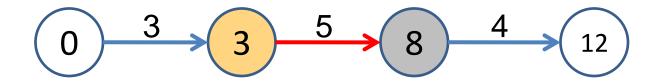






• Why n-1 time(s)?

3rd time

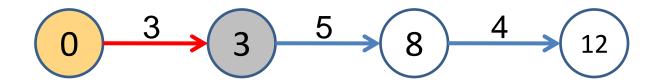






• Why n-1 time(s)?

3rd time







Pseudo code



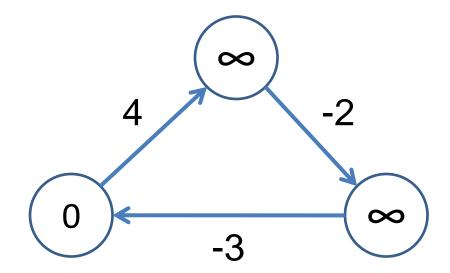


Practice1

POJ 2387 - Til the Cows Come Home

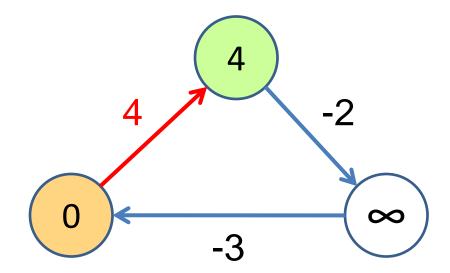






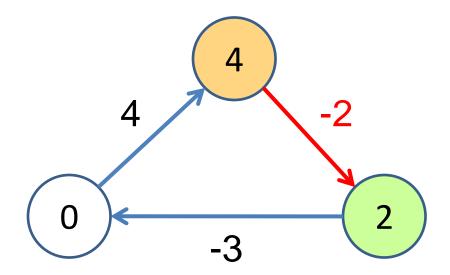






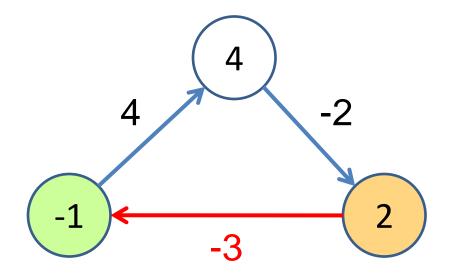






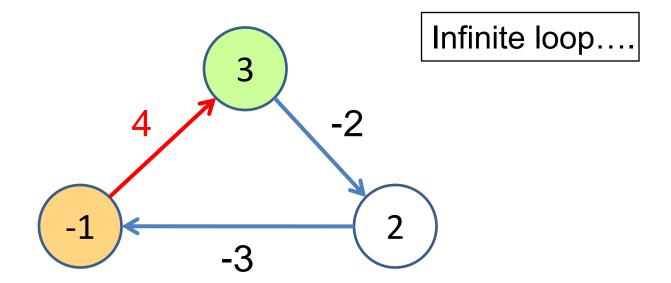
















- Relax 1 more time after n-1 times
 - If relax successfully, negative cycle exists.

- 若找到負環,是位於整張圖上的某處
 - Source不見得可以走的到該負環





Pseudo code

```
BellmanFord(){
        // Initialize
        dis[source]=0;
        dis[i]=INF, for all i!=source
        for(i=0;i<n-1;i++)
             for each edge w(u,v) in G
 9
                 Relax(u,v,w);
10
11
12
        for each edge w(u,v) in G
             if(dis[u]+w(u,v)<dis[v])</pre>
13
14
                 return true;
        return false;
```

分 63



Practice2

• POJ 3259 - Wormhole











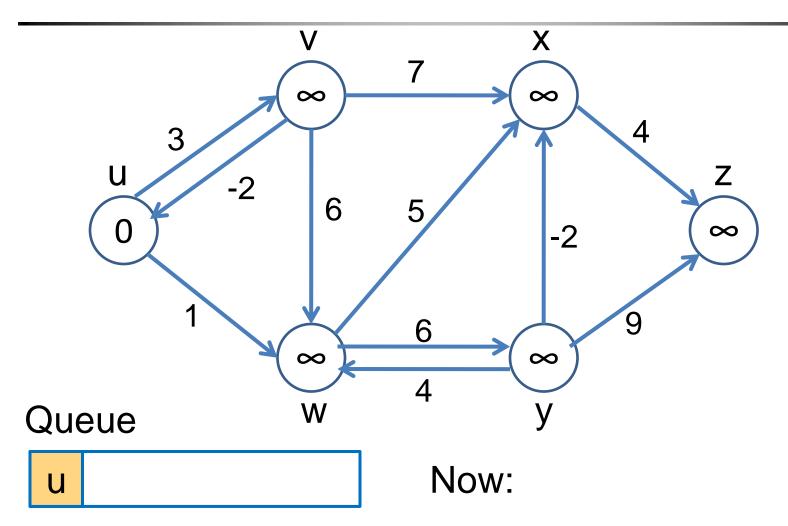
Shortest Path Faster Algorithm

- In Bellman Ford, relax n-1 times
 - Do we really need n-1 times…?
 - Only relax the one whose cost changed!

Queue

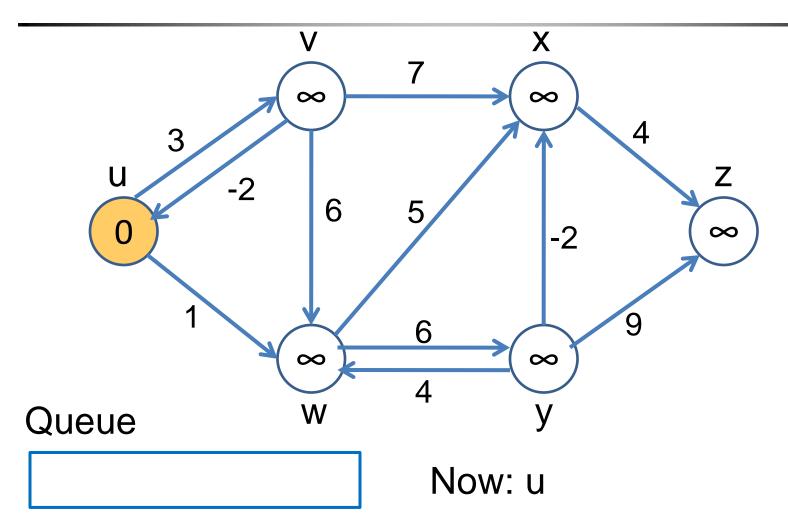






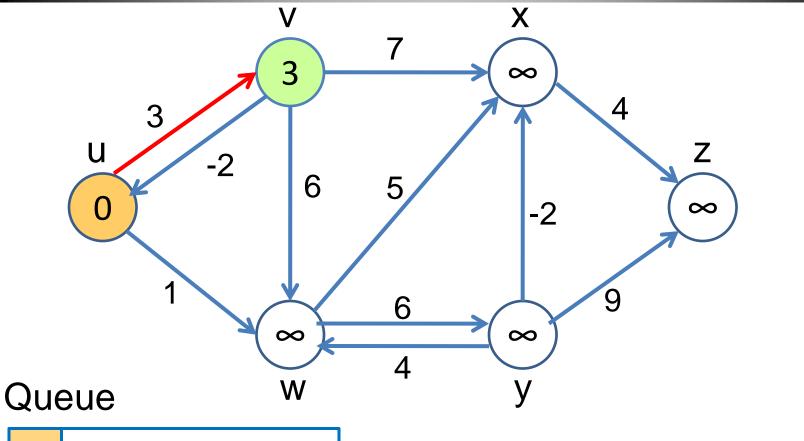










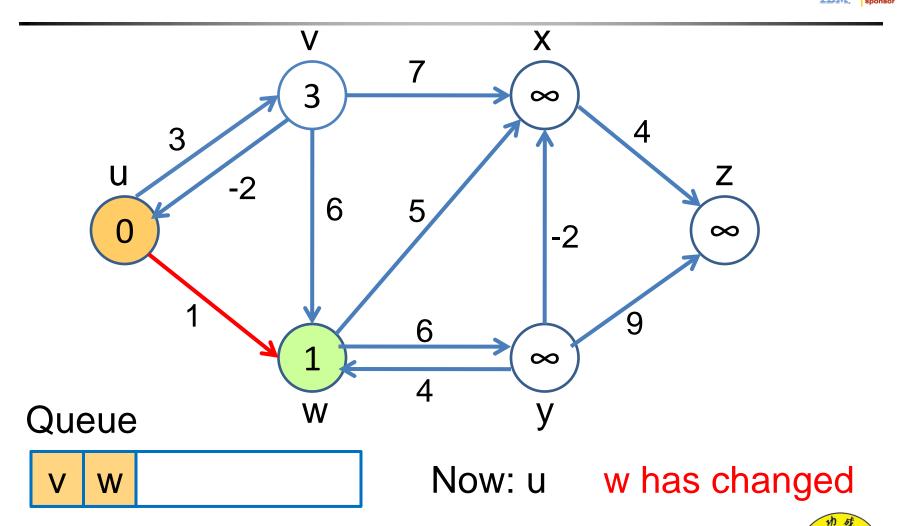


Now: u v has changed



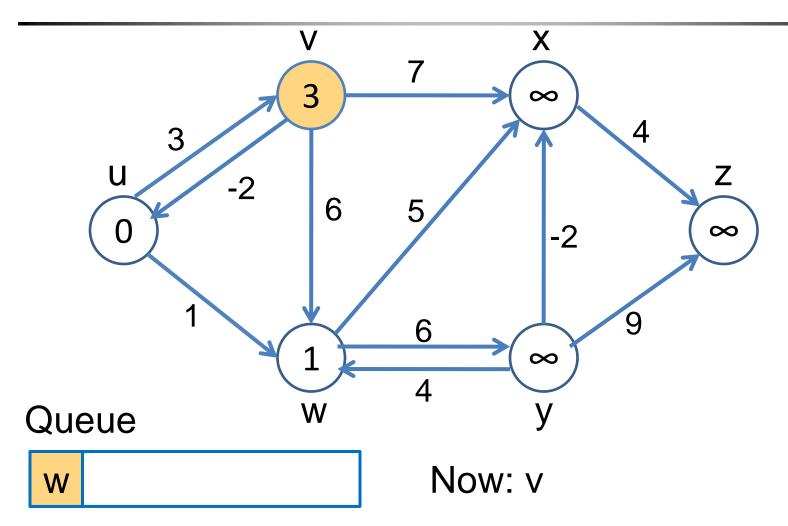
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SPFA





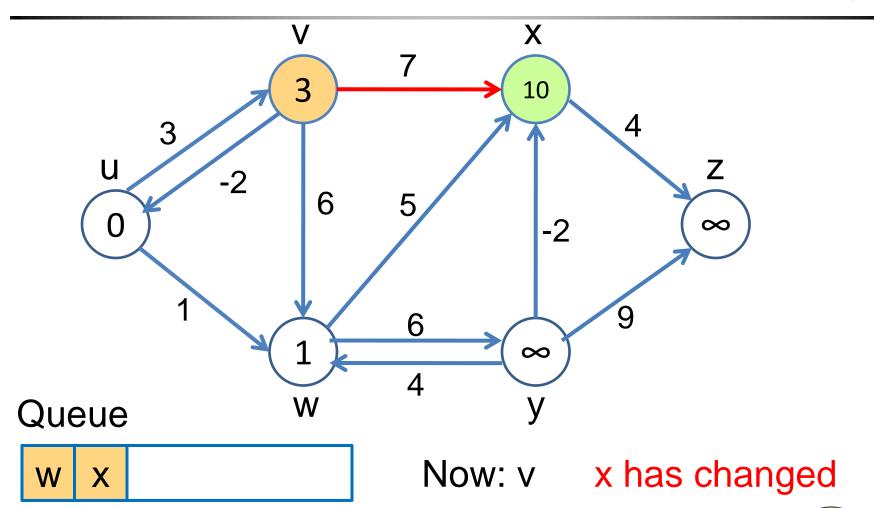




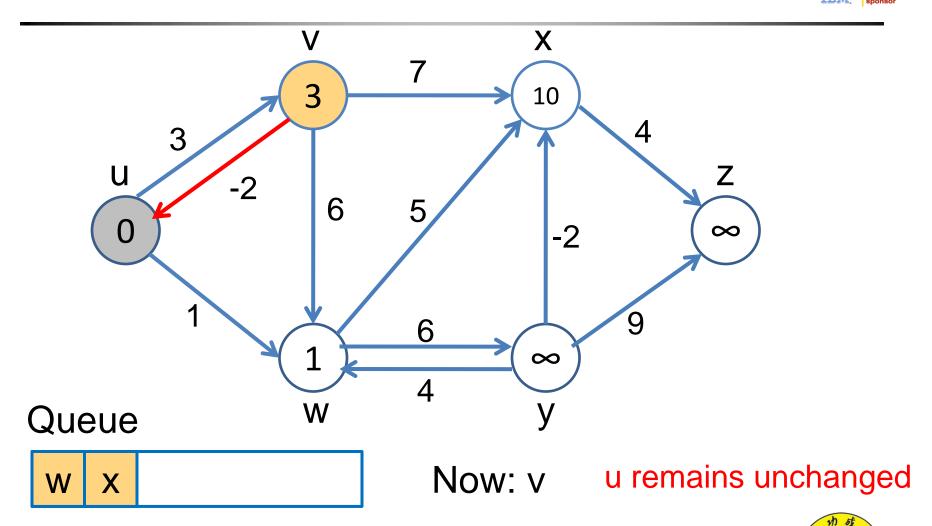


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SPFA

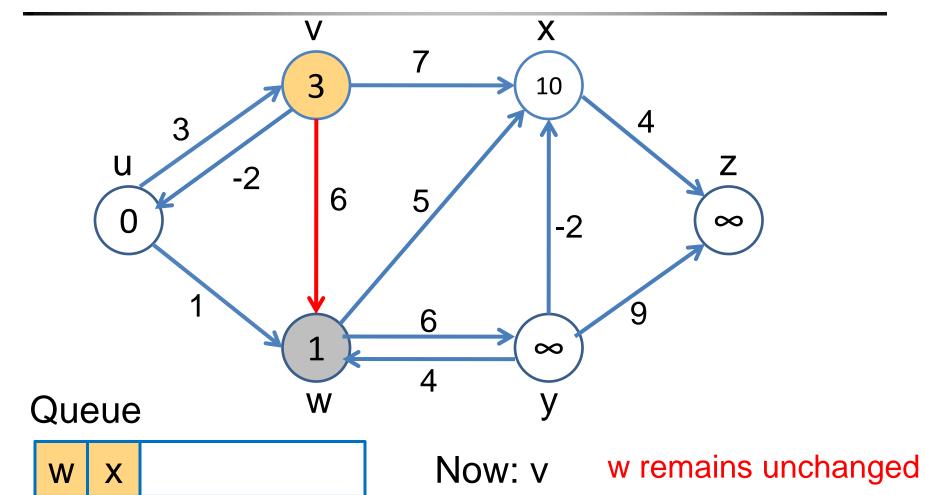


Competitive Algorithm Design and Practice





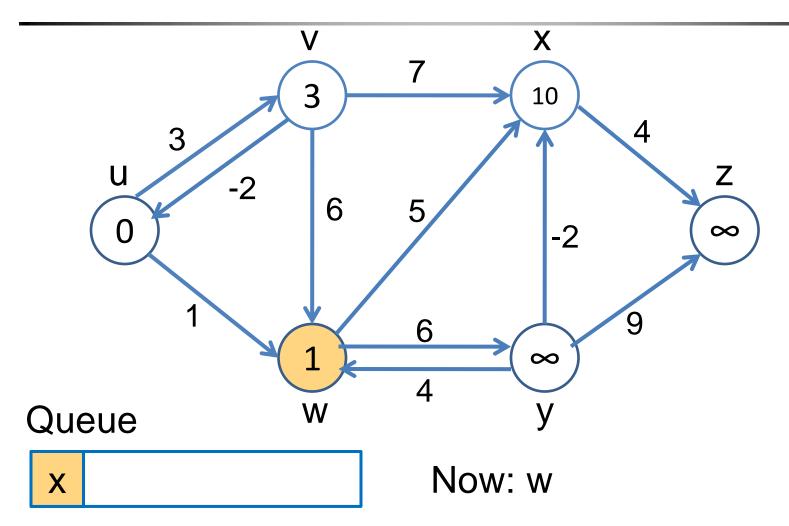
SPFA



Competitive Algorithm Design and Practice

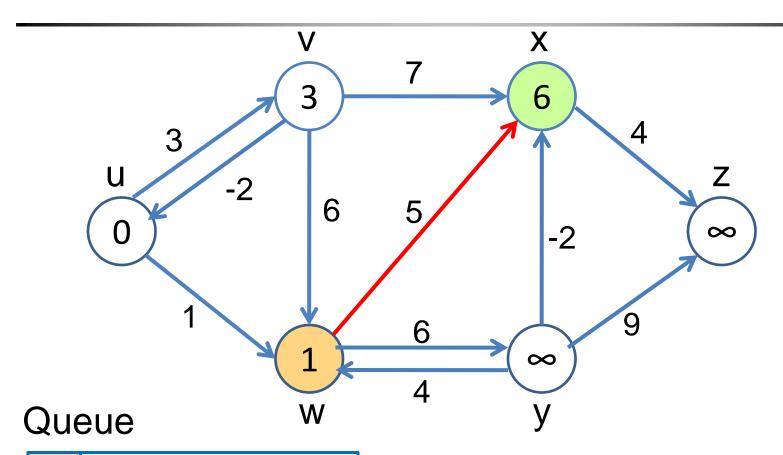












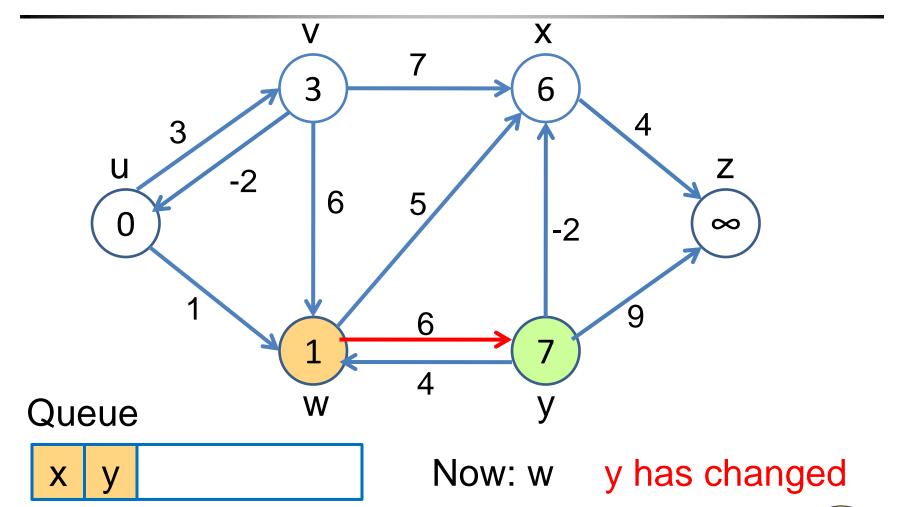
X

already in queue

Now: w x has changed

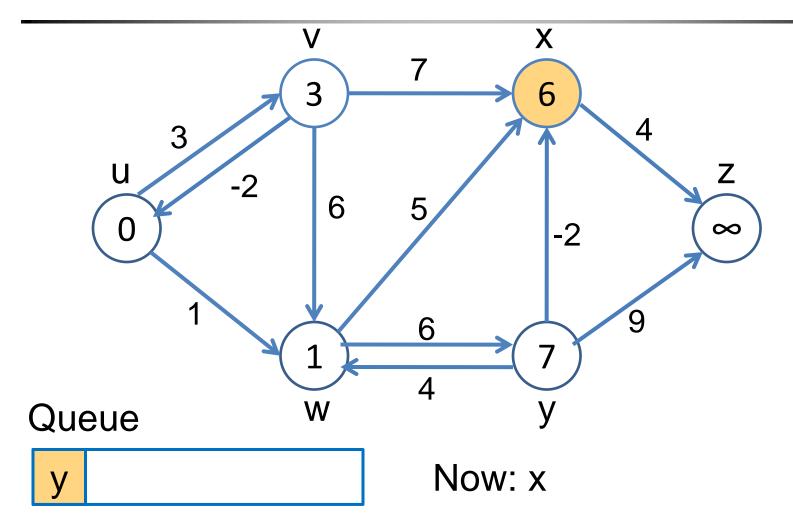


SPFA

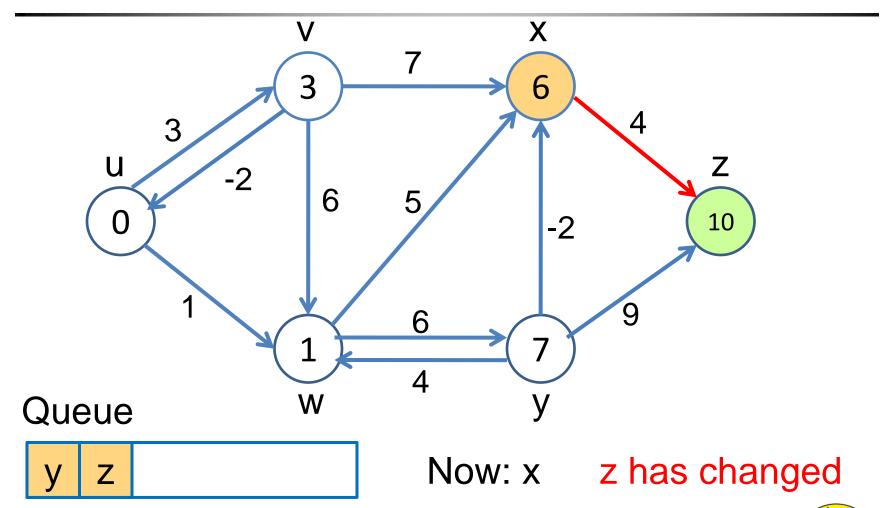


Competitive Algorithm Design and Practice



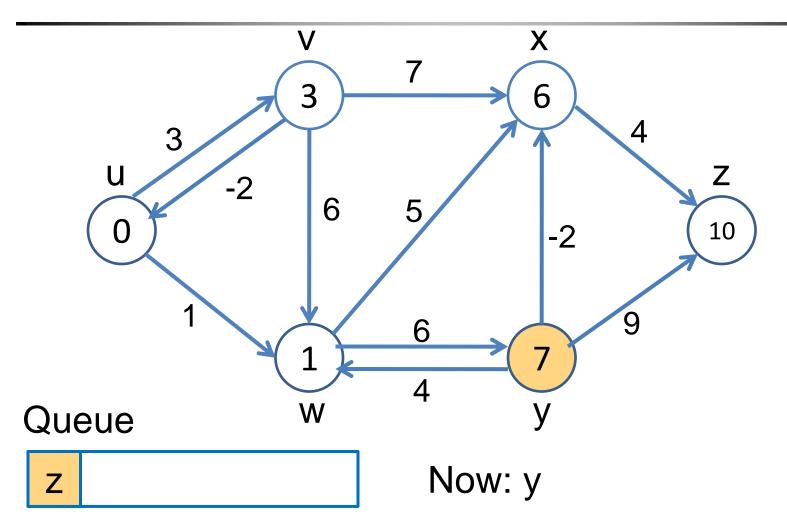






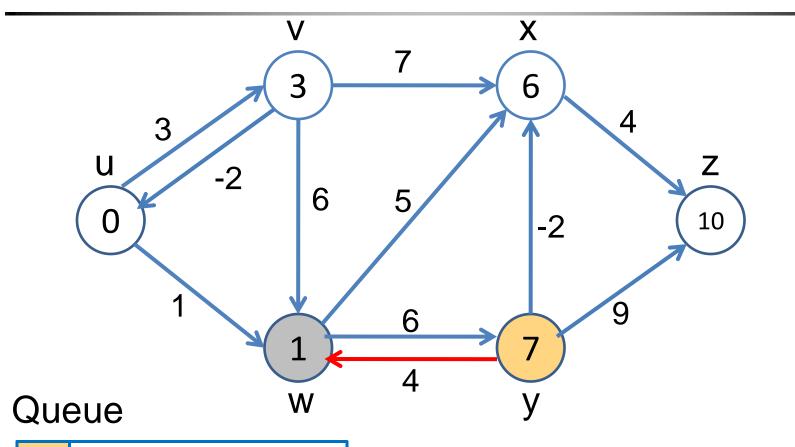








SPFA



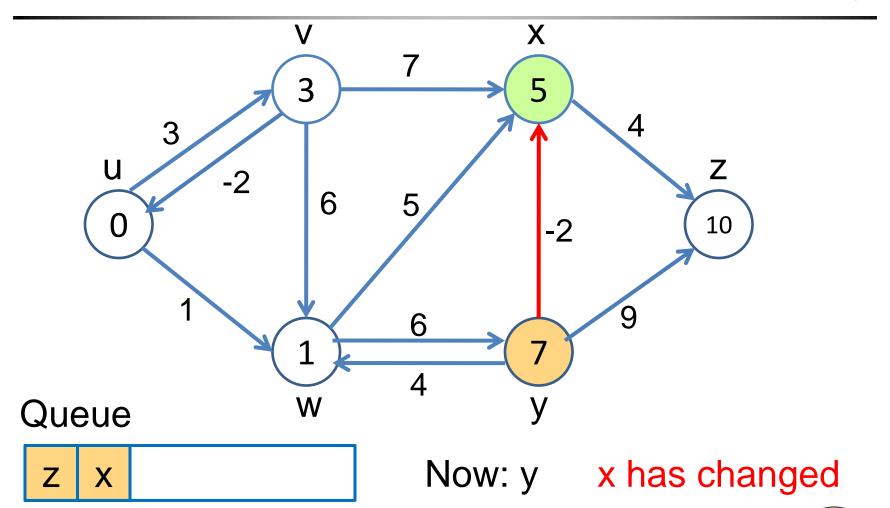
Z

Now: y

w remains unchanged



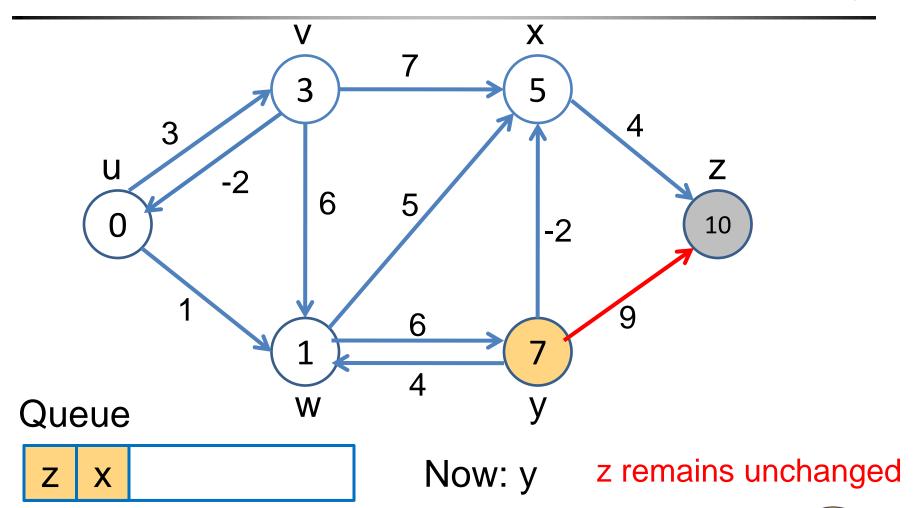
SPFA



Competitive Algorithm Design and Practice



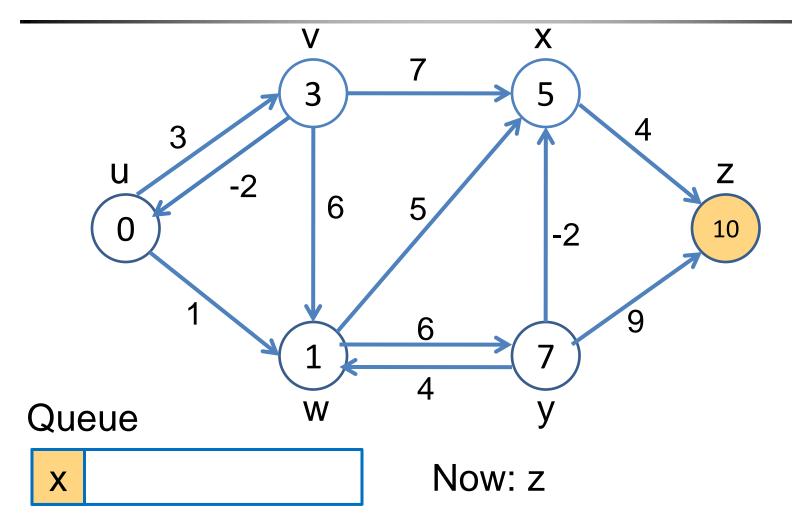
SPFA



Competitive Algorithm Design and Practice

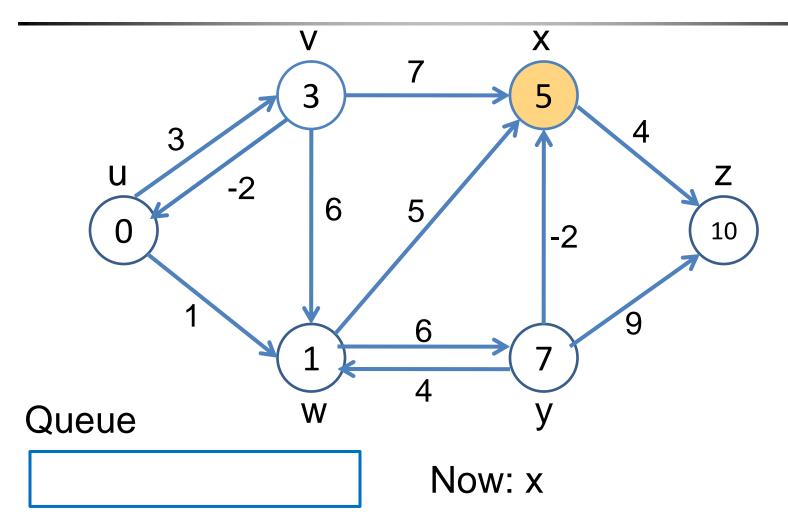






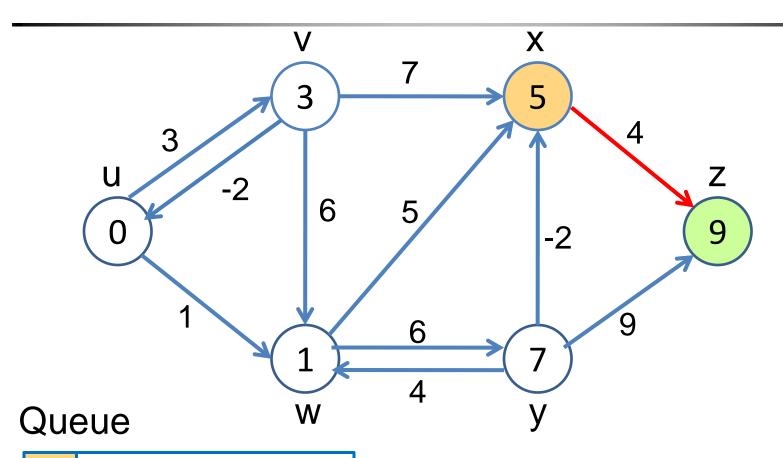










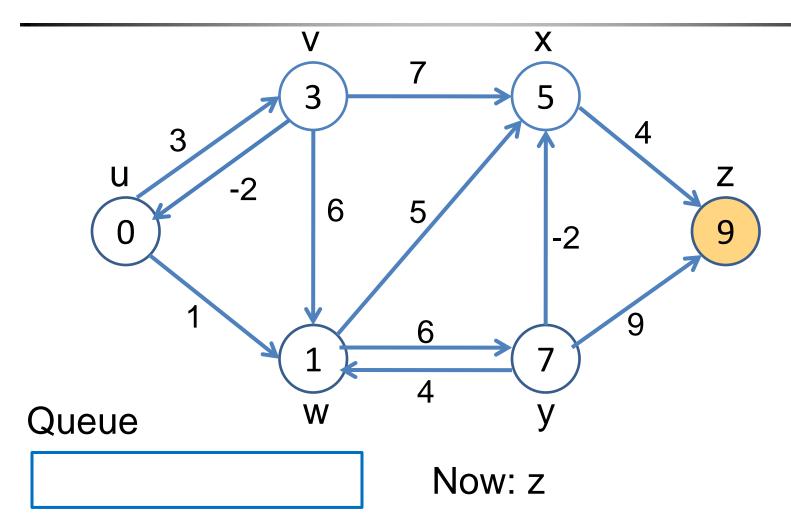


Z

Now: x z has changed

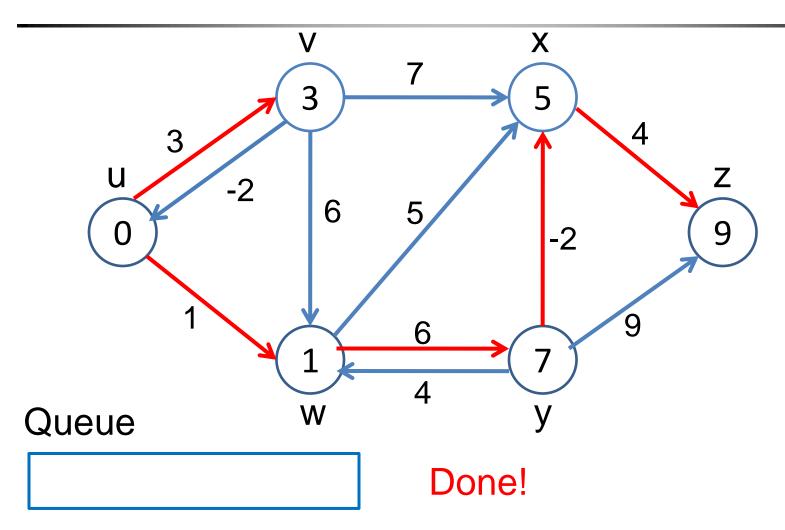














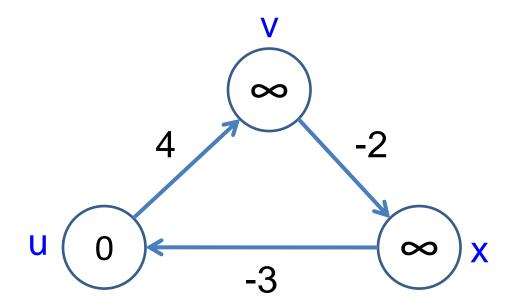


```
SPFA(){
        dis[i]=INF, inqueue[i]=false, for all i
        dis[source]=0;
 4
        inqueue[source]=true;
        queue.push(source);
        while(!queue.empty()){
 6
            now=queue.front();
 8
             inqueue[now]=false;
             queue.pop();
10
             for each node v adjacent to now{
                 if(dis[now]+w(now,v)<dis[v]){</pre>
11
                     dis[v]=dis[now]+w(now,v);
12
13
                     if(!inqueue[v]){
14
                         queue.push(v);
                          inqueue[v]=true;
15
16
17
18
19
20
```





Negative cycle?



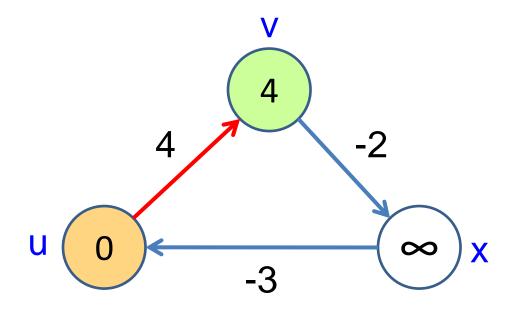
Queue

u





Negative cycle?



Queue



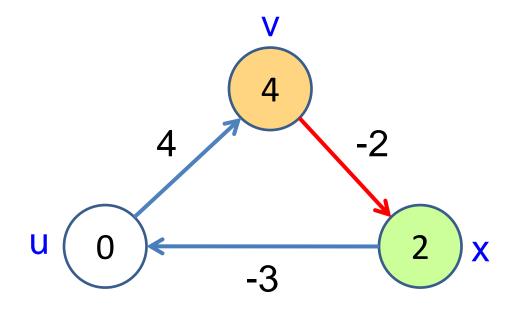
Now: u

v has changed





Negative cycle?



Queue



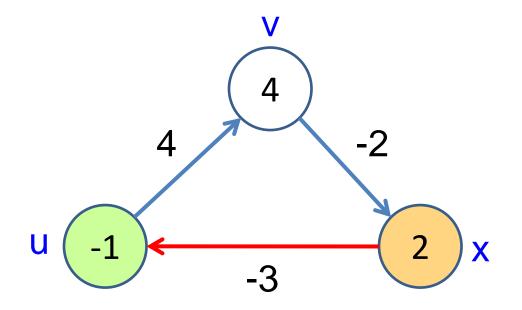
Now: v

x has changed





Negative cycle?



Queue

u

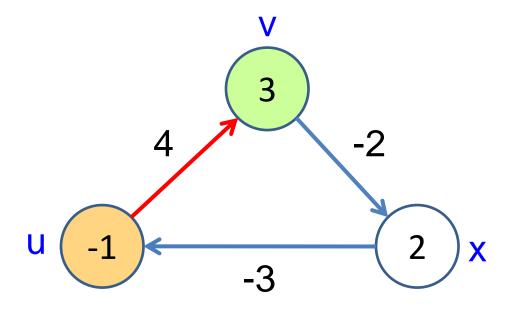
Now: x

u has changed





Negative cycle?



Queue



Now: u

v has changed

Infinite Loop...





- Count the times of pushing a node in queue
 - No more than n-1 times
 - Otherwise, negative cycle exists.

- 若找到負環,必是由source出發後遇到的負環
 - source走不到的地方無從得知





```
SPFA(){
        dis[i]=INF, inqueue[i]=false, count[i]=0 for all i
        dis[source]=0;
        inqueue[source]=true;
        queue.push(source);
        while(!queue.empty()){
            now=queue.front();
            inqueue[now]=false;
            queue.pop();
 9
10
             for each node v adjacent to now{
                 if(dis[now]+w(now,v)<dis[v]){</pre>
11
12
                     dis[v]=dis[now]+w(now,v);
13
                     if(!inqueue[v]){
14
                         queue.push(v);
15
                         inqueue[v]=true;
16
                         count[v]++;
                         if(count[v]>=n) return true;
18
19
20
21
22
        return false;
```

Competitive Algorithm Design and Practice





- Complexity
 - O(kE), where k<<V, for average case</p>
 - O(VE), for worst case





Bellman Ford vs SPFA

	Bellman Ford	SPFA
Edge	Discrete data structure	Adjacency list
Negative cycle	Some where in Graph	From source
Complexity	O(VE)	O(kE)





All Pair Shortest Path



APSP



- How?
 - Bellman Ford * V times: O(V²E)
 - SPFA * V times: O(kVE)

- Floyd-Warshall algorithm
 - $-O(V^3)$







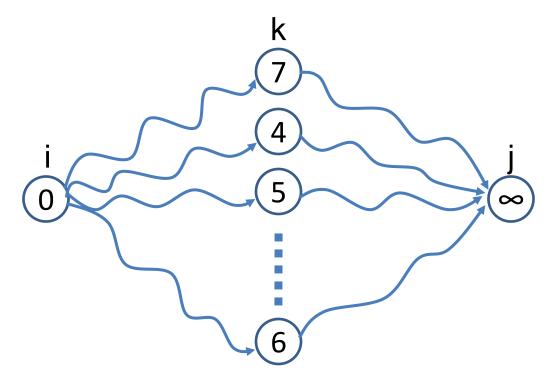
- Enumerate all node k as relay point
 - Repeat for each pair(i,j)







- Enumerate all node k as relay point
 - Repeat for each pair(i,j)

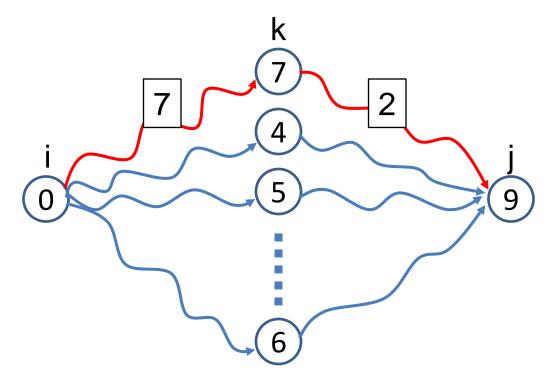








- Enumerate all node k as relay point
 - Repeat for each pair(i,j)

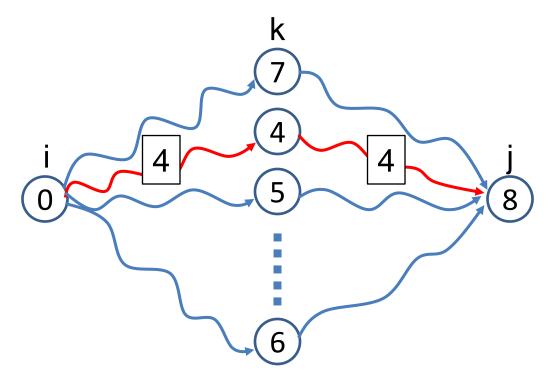








- Enumerate all node k as relay point
 - Repeat for each pair(i,j)

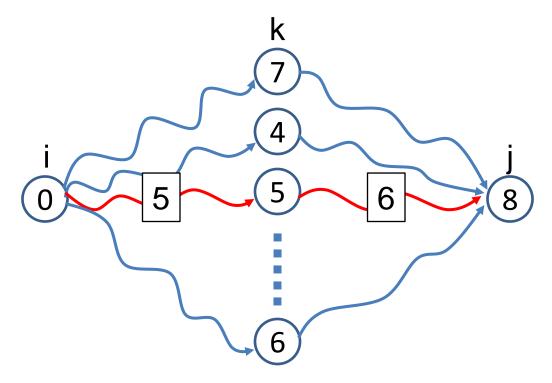






Floyd

- Enumerate all node k as relay point
 - Repeat for each pair(i,j)

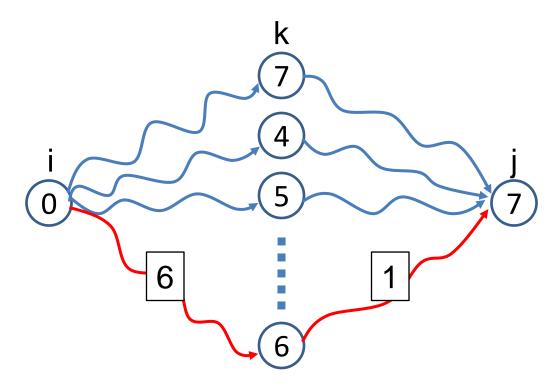








- Enumerate all node k as relay point
 - Repeat for each pair(i,j)







Floyd

Pseudo code

```
1 Floyd(){
2    dis[i][j]=0, for i=j
3    dis[i][j]=w(i,j), for each edge w(i,j)
4    dis[i][j]=INF, otherwise.
5    for(k=0;k<n;k++)
6         for(i=0;i<n;i++)
7         for(j=0;j<n;j++)
8         if(dis[i][k]+dis[k][j]<dis[i][j])
9         dis[i][j]=dis[i][k]+dis[k][j];
10 }</pre>
```







- Complexity
 - $-O(V^3)$







- Complexity
 - $-O(V^3)$

- How about multiple edges between (a,b)?
 - Use the shortest one





Practice3

POJ 1125 - Stockbroker Grapevine







Summary

- SSSP:
 - Bellman Ford
 - SPFA
 - Dijkstra (Google it by yourself)

- APSP:
 - Floyd
 - SPFA * V times (Sometimes better than Floyd)





- How to output one of shortest paths?
 - Table: record the previous one



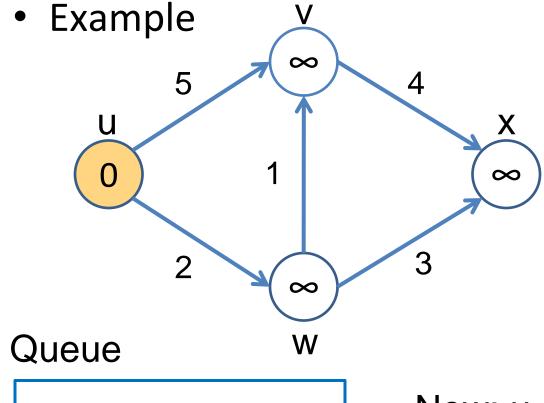


- How to output one of shortest paths?
 - Table: record the previous one

Once relax successfully, update prev[id].





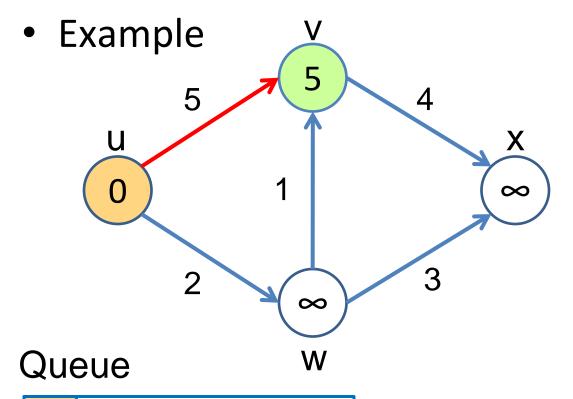


id	prev[id]
u	None
V	None
W	None
X	None

Now: u







id	prev[id]
u	None
V	u
W	None
X	None

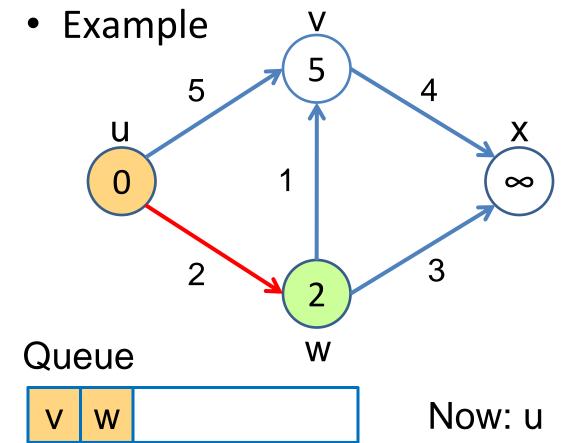
V

Now: u





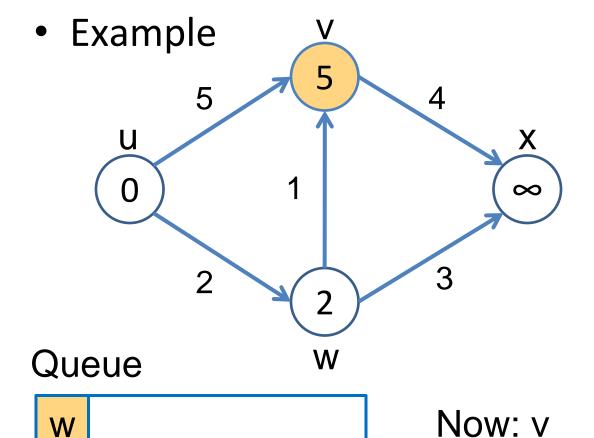




id	prev[id]
u	None
V	u
W	u
X	None



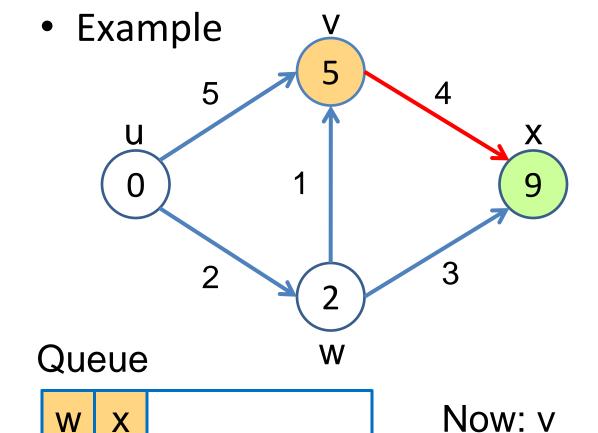




id	prev[id]
u	None
V	u
W	u
X	None

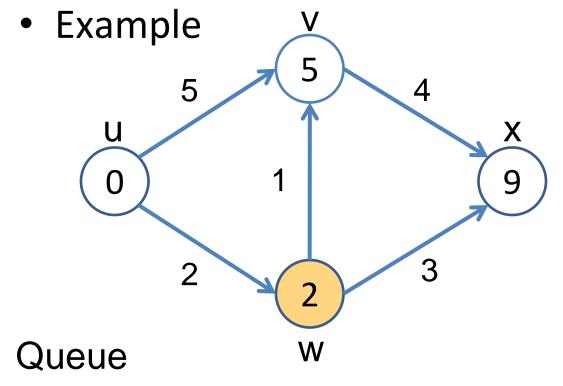






id	prev[id]
u	None
V	u
W	u
X	V





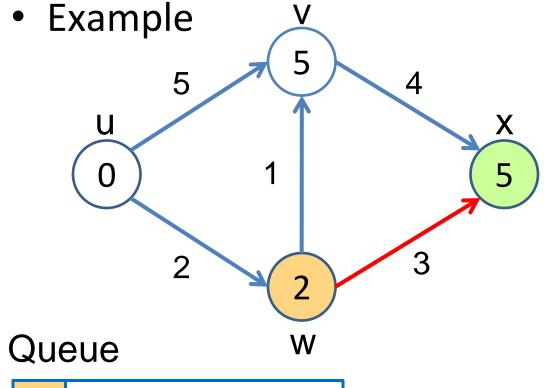
id	prev[id]
u	None
V	u
W	u
X	V

X

Now: w







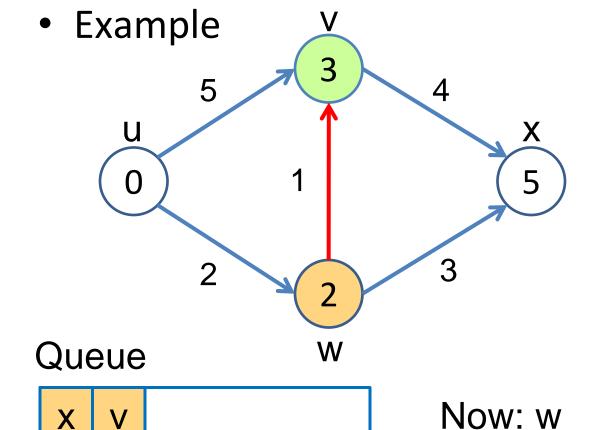
id	prev[id]
u	None
V	u
W	u
X	W

X

Now: w



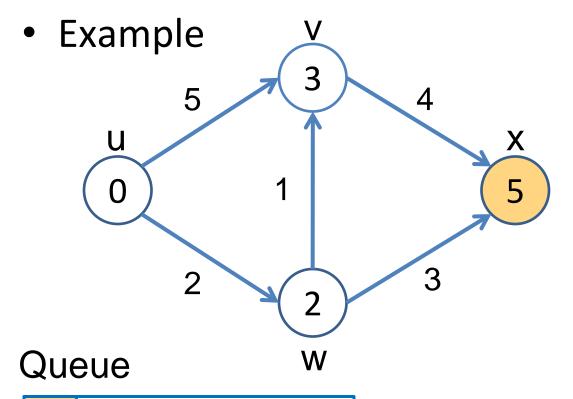




id	prev[id]
u	None
V	W
W	u
X	W







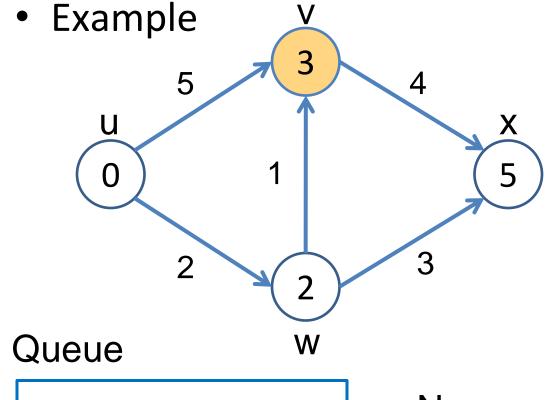
id	prev[id]
u	None
V	W
W	u
X	W

V

Now: x





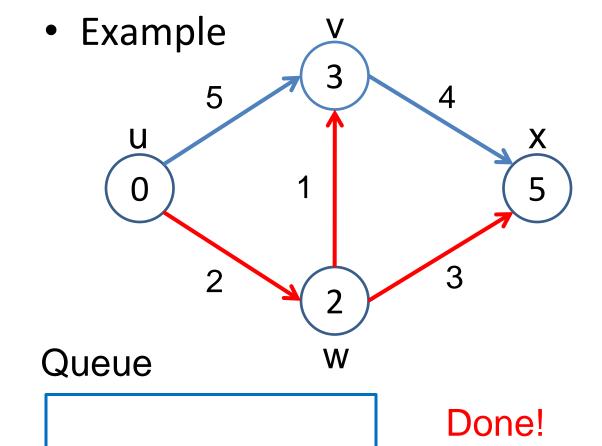


id	prev[id]
u	None
V	W
W	u
X	W

Now: v







id	prev[id]
u	None
V	W
W	u
X	W





Thank you for your attention!

