

Competitive Algorithm Design and Practice

Bipartite Matching

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Outline

- Pre-concept
 - Matching
 - Cardinality vs Weighted
 - Bipartite Graph
- Maximum Cardinality Bipartite Matching
 - Flow Modeling
 - Alternating Path
 - Augmenting Path Algorithm



Matching



Matching

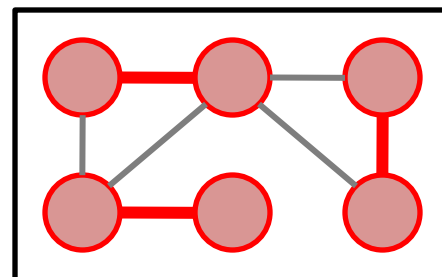
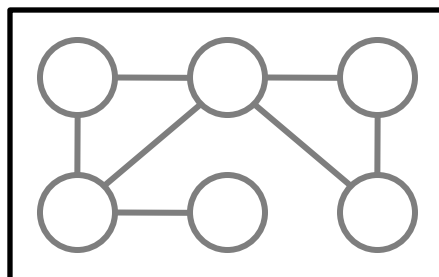
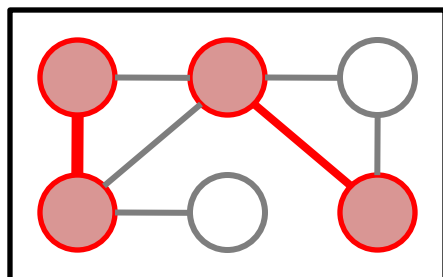
- 匹配
- A set of edges in a graph without common vertices.



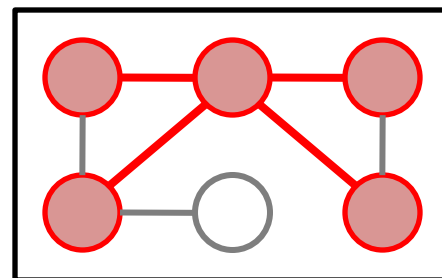
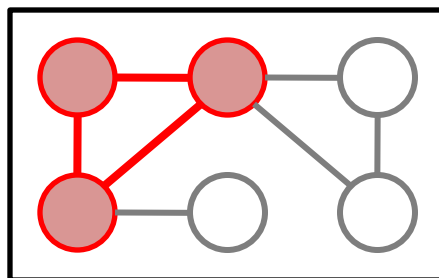
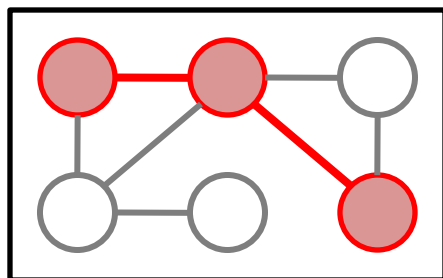
Matching

- 匹配
- A set of edges in a graph without common vertices.

Matching



Not Matching

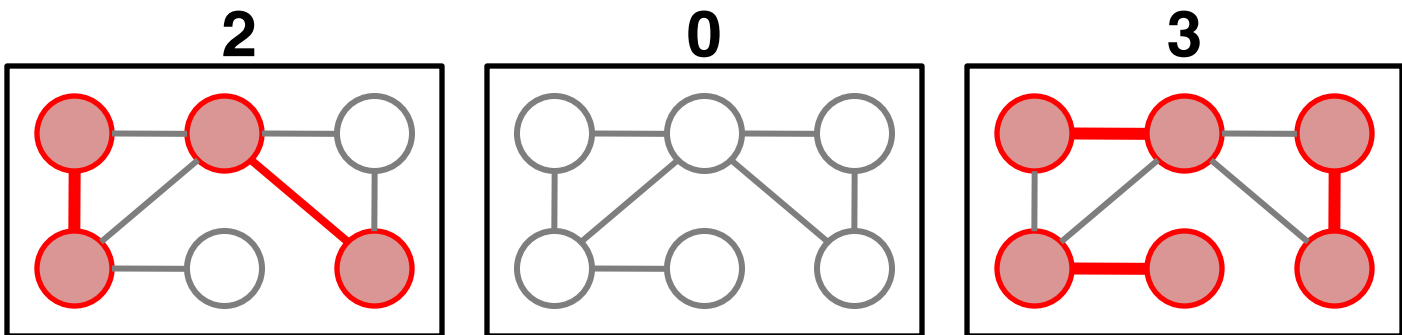


Cardinality vs Weighted

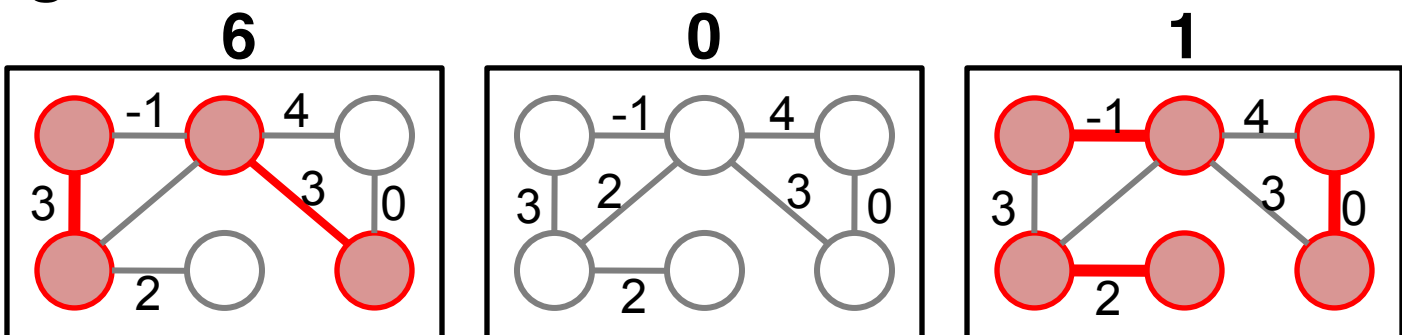


Cardinality vs Weighted

- Cardinality: 個數



- Weighted: 權重



Matching

- Maximum (Cardinality) Matching
 - 最大匹配數
- Maximum Weighted Matching
 - 最大總權重
- Maximum Weighted Maximum Cardinality Matching
 - 最大匹配數的前提下，最大總權重
- And so on...

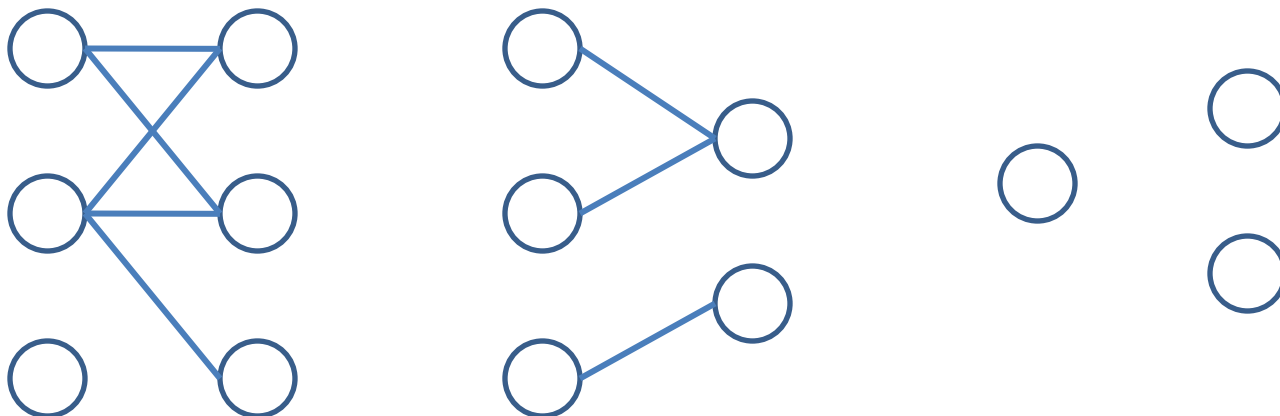


Bipartite Graph



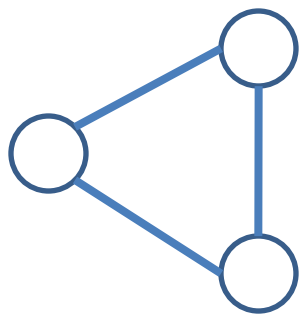
Bipartite Graph

- 二分圖
- 可以分成兩群，每群內彼此間沒有edge

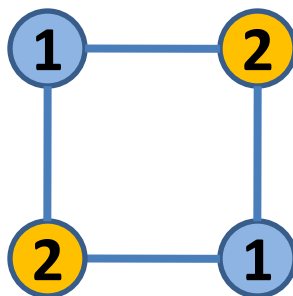


Bipartite Graph

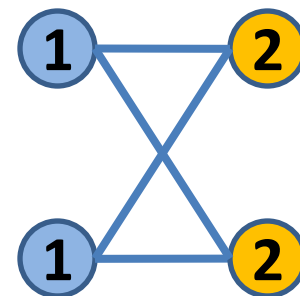
- 或者，一張圖上不存在odd (length) cycle
- 若給一張不存在odd cycle的圖，可用DFS/BFS標號將圖分成兩群



odd cycle



even cycle



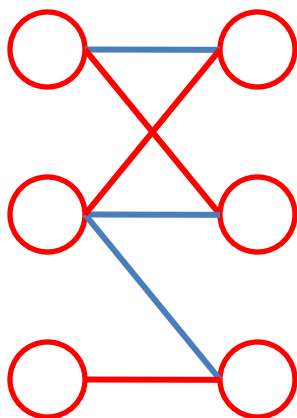
Bipartite Graph

Maximum Cardinality Bipartite Matching

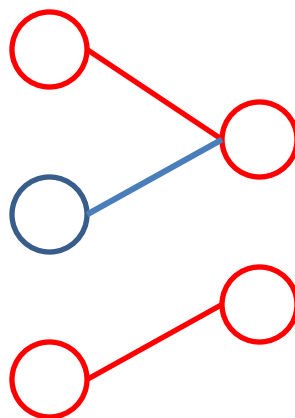


Maximum Bipartite Matching

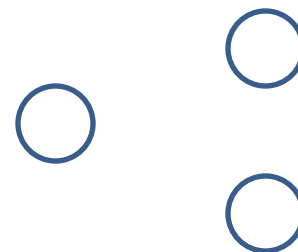
- 二分圖最大匹配(數)



3



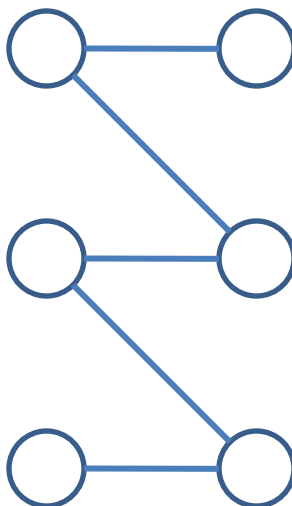
2



0

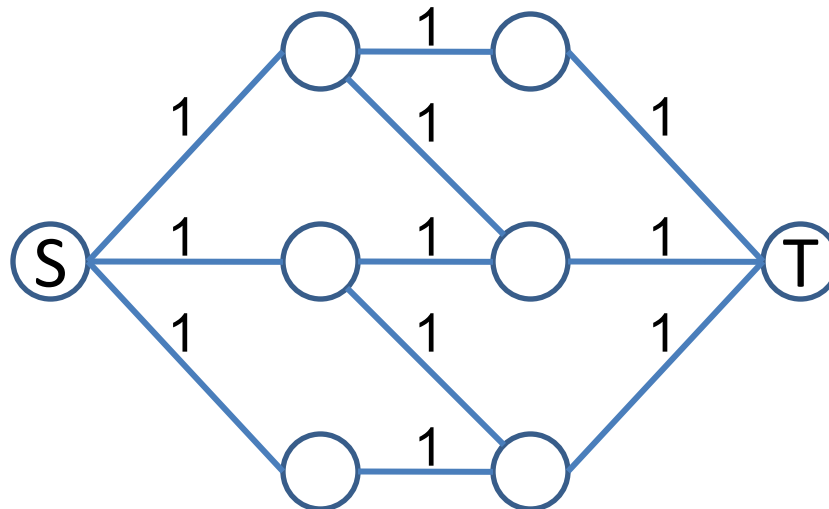
Maximum Bipartite Matching

- Flow modeling



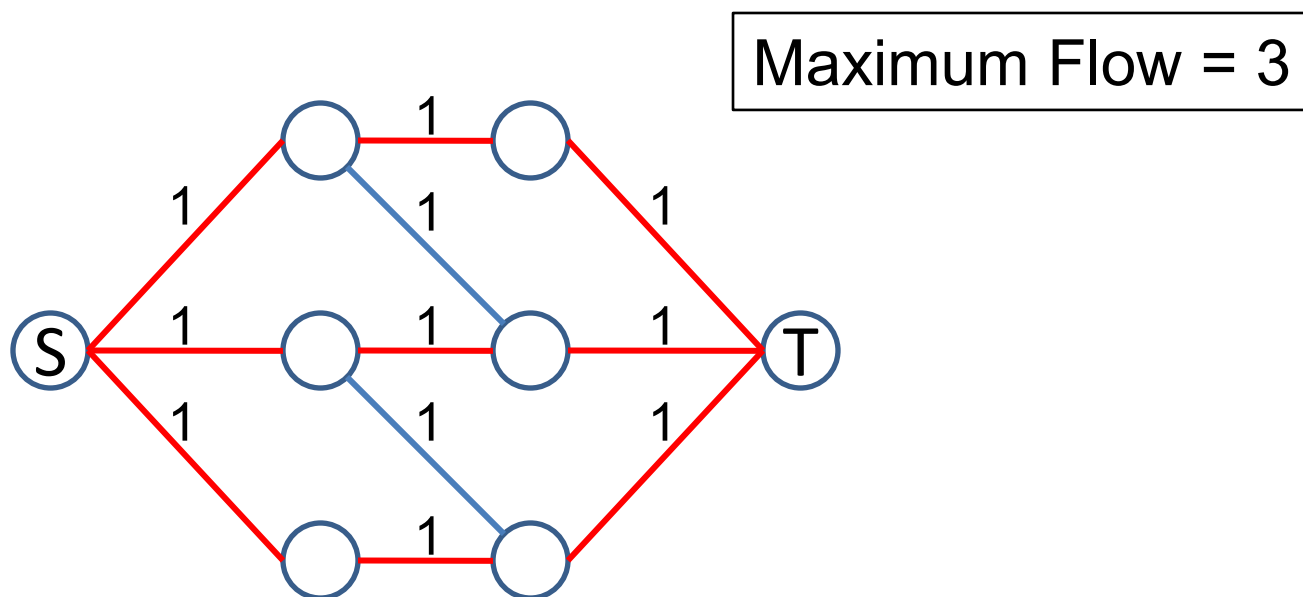
Maximum Bipartite Matching

- Flow modeling



Maximum Bipartite Matching

- Flow modeling



Maximum Bipartite Matching

- Flow modeling
 - Edmonds-Karp: $O(VE^2)$
 - Dinic: $O(V^2E)$

- Faster algorithm...?

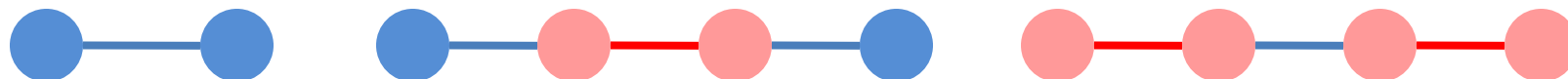


Augmenting Path Algorithm



Augmenting Path Algorithm

- Alternating Path (交錯路徑)
 - 匹配邊與未匹配邊交替出現的路徑



Augmenting Path Algorithm

- Augmenting Path(增廣路徑)
 - 起點與終點都是未匹配點的alternating path



Yes



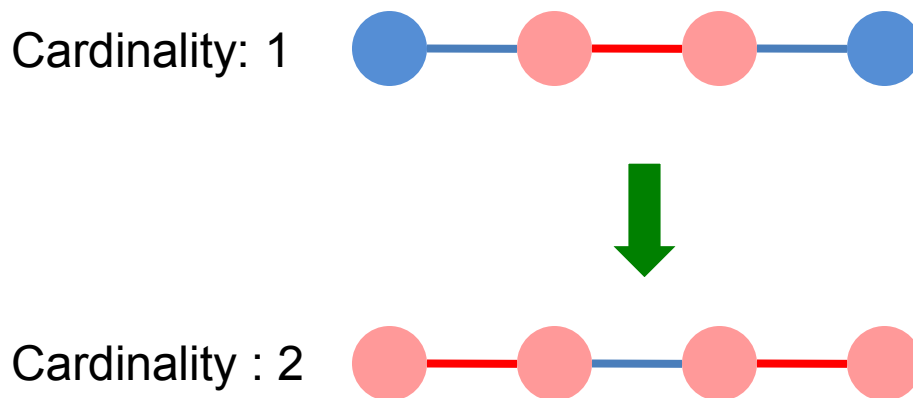
Yes



No

Augmenting Path Algorithm

- 觀察：
 - 將augmenting path的匹配邊與未匹配邊對調，
匹配數量**加1**，且不影響匹配正確性



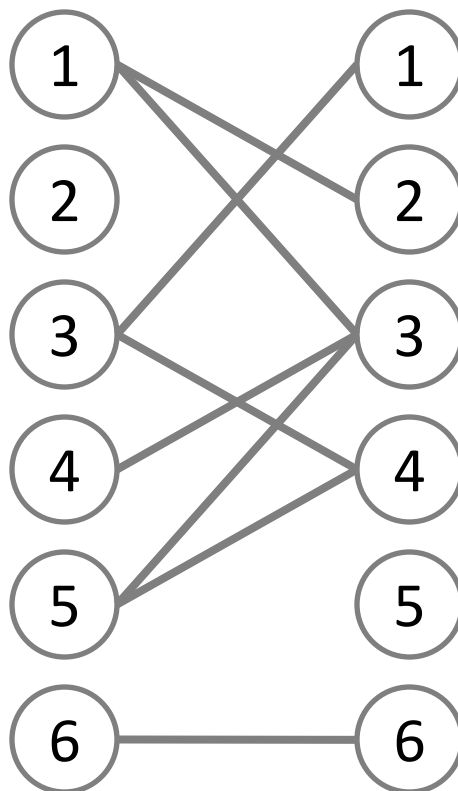
Augmenting Path Algorithm

- Algorithm:
 1. 枚舉左邊這群的每個點，嘗試找尋augmenting path
 2. 每次找到augmenting path，對調匹配與未匹配邊



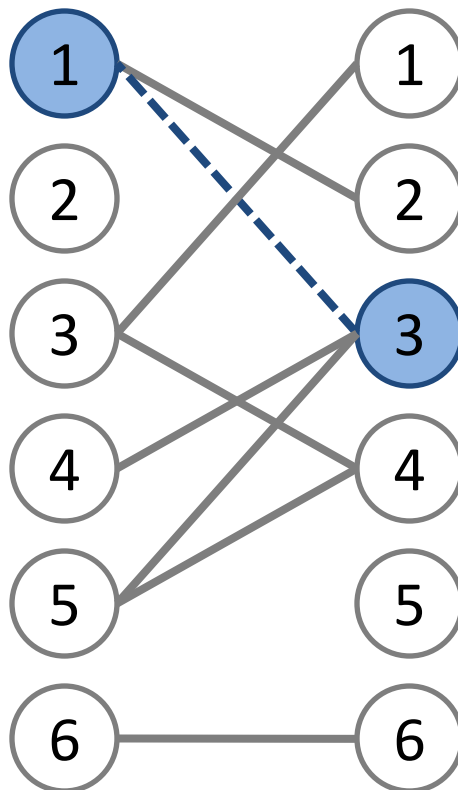
Augmenting Path Algorithm

- Example



Augmenting Path Algorithm

- Example

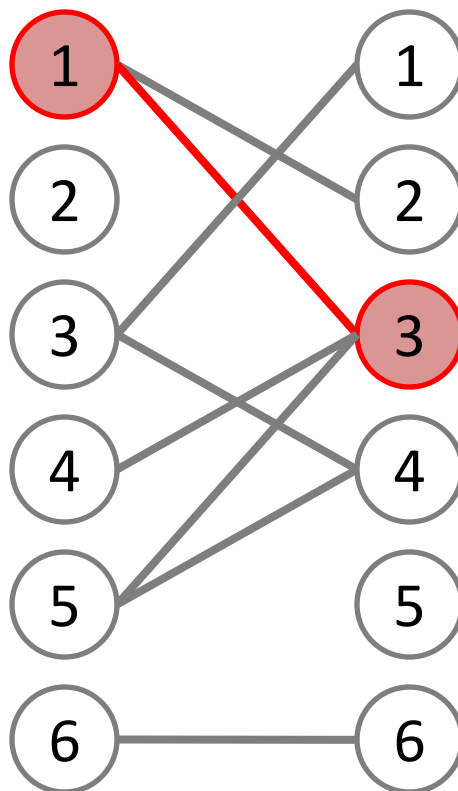


找到augmenting path:
1-3



Augmenting Path Algorithm

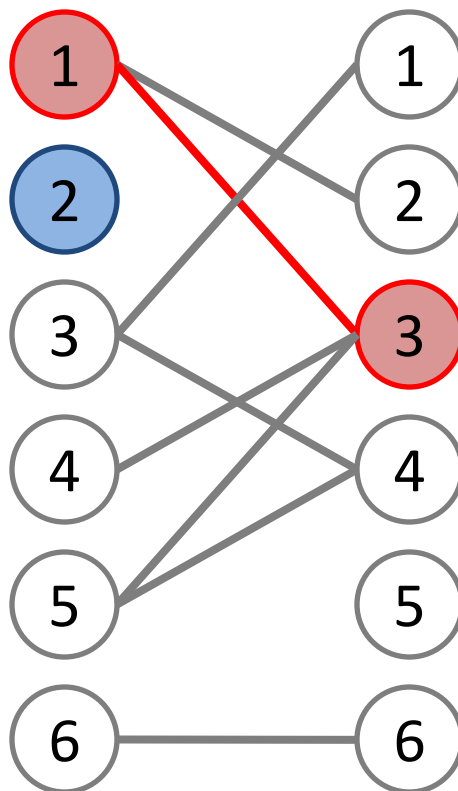
- Example



對調，匹配數+1

Augmenting Path Algorithm

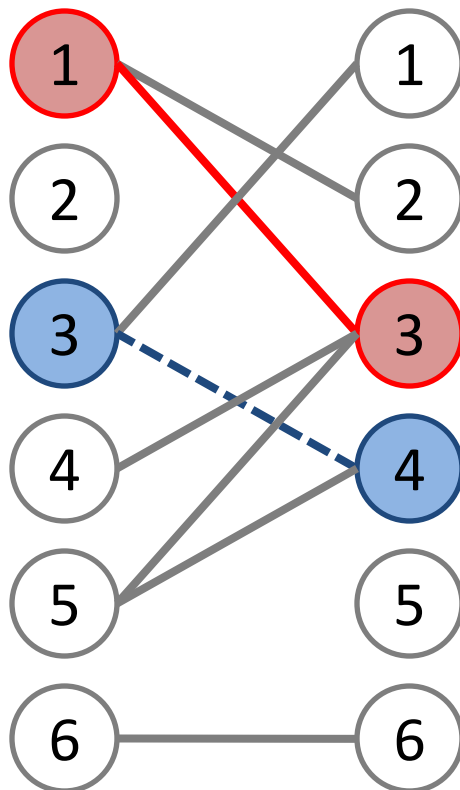
- Example



沒有augmenting path

Augmenting Path Algorithm

- Example

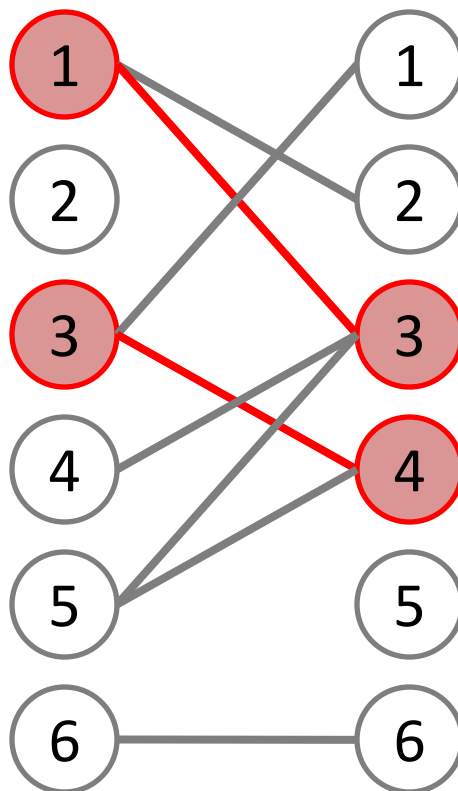


找到augmenting path:
3-4



Augmenting Path Algorithm

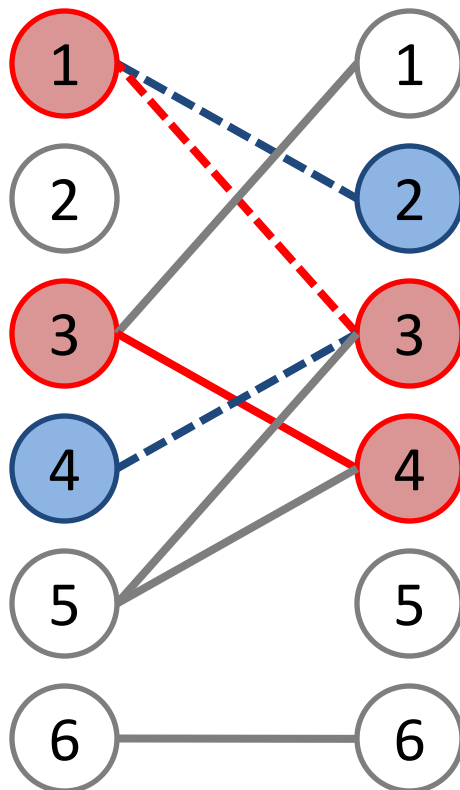
- Example



對調，匹配數+1

Augmenting Path Algorithm

- Example

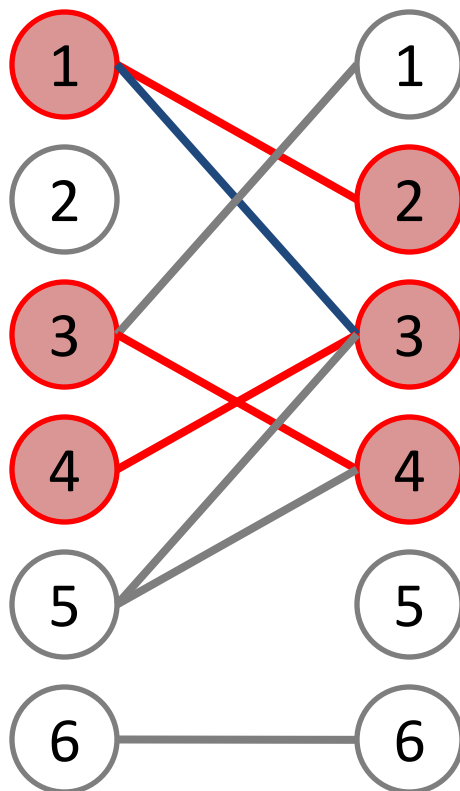


找到augmenting path:
4-3-1-2



Augmenting Path Algorithm

- Example

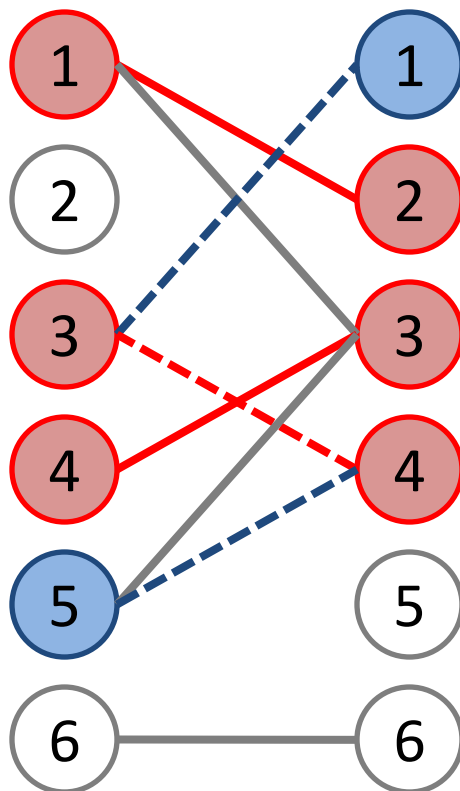


對調，匹配數+1



Augmenting Path Algorithm

- Example

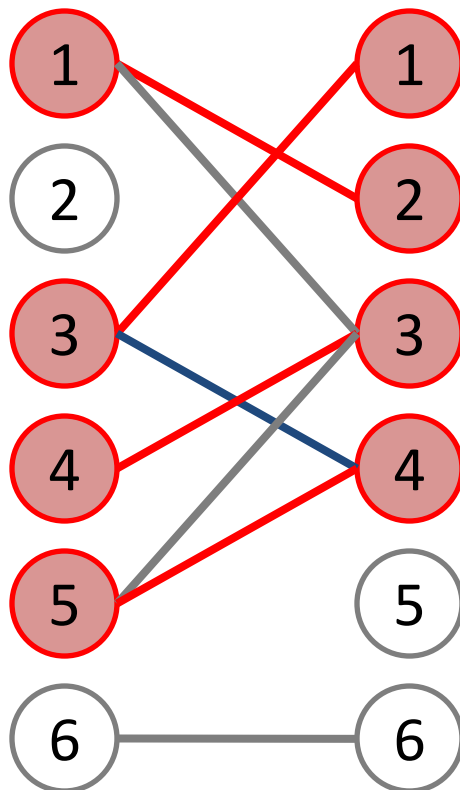


找到augmenting path:
5-4-3-1



Augmenting Path Algorithm

- Example

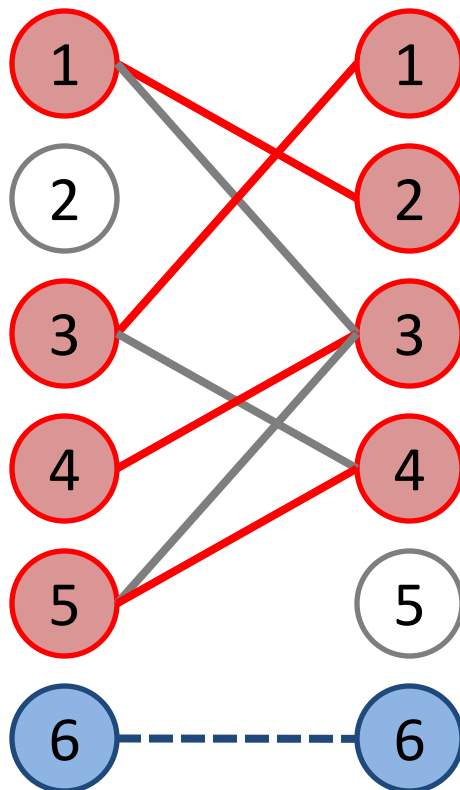


對調，匹配數+1



Augmenting Path Algorithm

- Example

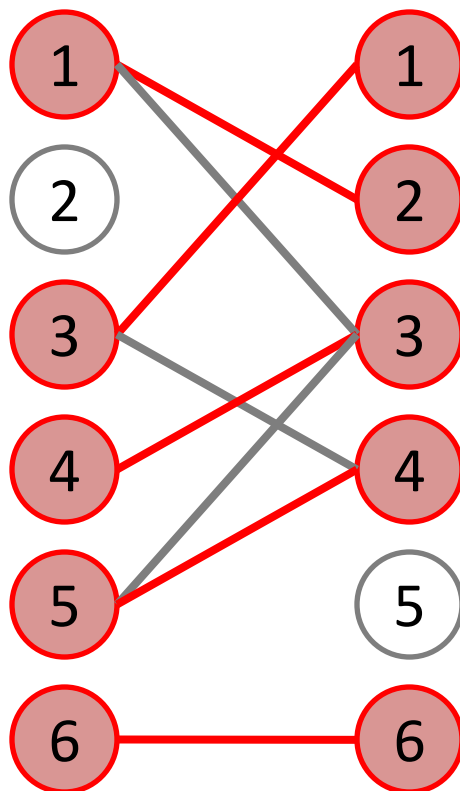


找到augmenting path:
6-6



Augmenting Path Algorithm

- Example

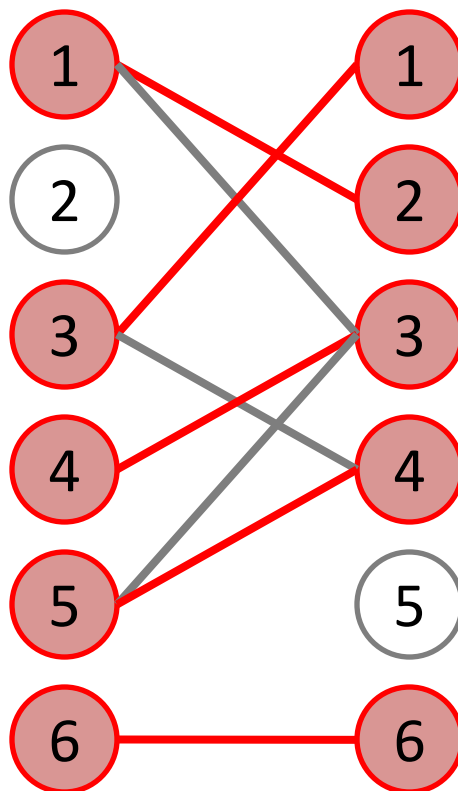


對調，匹配數+1



Augmenting Path Algorithm

- Example



最大匹配數: 5

1-2

3-1

4-3

5-4

6-6

Augmenting Path Algorithm

- 找augmenting path:
 - Backtracking?



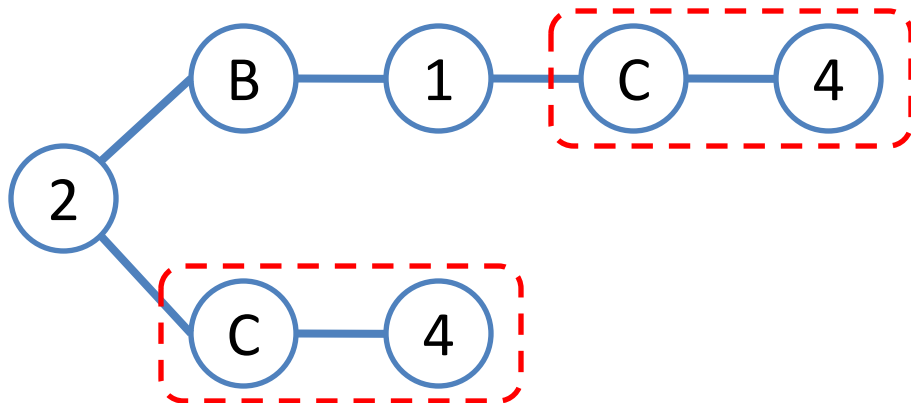
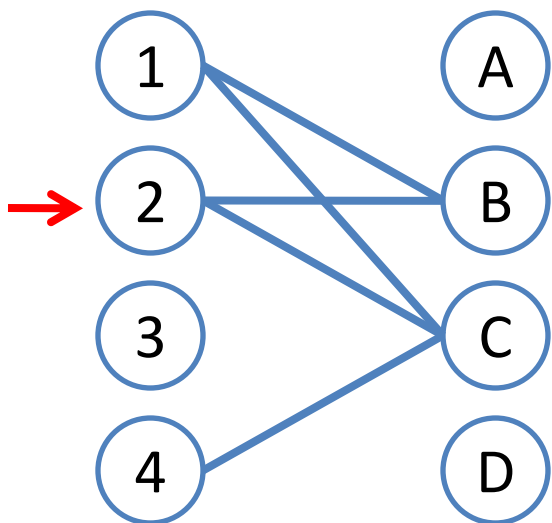
Augmenting Path Algorithm

- 找augmenting path:
 - Backtracking? **NO!**
 - **DFS/BFS!** Why?



Augmenting Path Algorithm

- 找augmenting path:
 - Backtracking? **NO!**
 - **DFS/BFS!** Why?



對於右邊visit過的點，不需要重新visit

Augmenting Path Algorithm

- Code

```
44 // Maximum Bipartite Matching
45 int Bipartite(int nL,int nR)
46 {
47     int i,ans=0;
48
49     // Numbering from 1 to nL/nR
50     memset(llink,0,(nL+1)*sizeof(int));
51     memset(rlink,0,(nR+1)*sizeof(int));
52
53     // Try all vertices on the left side
54     for(i=1;i<=nL;++i)
55     {
56         // Visit once only
57         memset(used,false,(nR+1)*sizeof(bool));
58         if(DFS(i)) ++ans;
59     }
60     return ans;
61 }
```



Augmenting Path Algorithm

- Code

```
14 // Augumenting Path
15 bool DFS(int now)
16 {
17     int i,next;
18
19     // Try all vetices on the right side
20     for(i=0;i<(int)edg[now].size();++i)
21     {
22         next=edg[now][i];
23
24         // Visit once only
25         if(!used[next])
26         {
27             used[next]=true;
28
29             // Unmatched vertex, or augmenting path found
30             if(!rlink[next]||DFS(rlink[next]))
31             {
32                 // Update matching
33                 llink[now]=next;
34                 rlink[next]=now;
35                 return true;
36             }
37         }
38     }
39
40     // No augmenting path is found
41     return false;
42 }
```



Practice

- UVa 10080
 - 或POJ 2536



Thank you for your attention!

